

Bellman Ford algorithm for SSSP

$\delta(u, v)$ is the shortest path distance between vertices u to v

$u \rightsquigarrow v$ is the notation for a path from u to v

$\delta(s, v)$ is the final output of the algorithm for all v

$D(v)$: is an upper bound on $\delta(s, v)$

Initially $D(v) = \infty$, $D(s) = 0$
 $= \delta(s, s)$

Finally $D(v) = \delta(s, v)$

Relax (u, v) $(u, v) \in E$

If $D(v) > D(u) + w(u, v)$

then $D(v) \leftarrow D(u) + w(u, v)$

Repeat $(V-1)$ times

$\text{Pred}(v) \leftarrow u$

[for all edges $(u, v) \in E$

for path construction

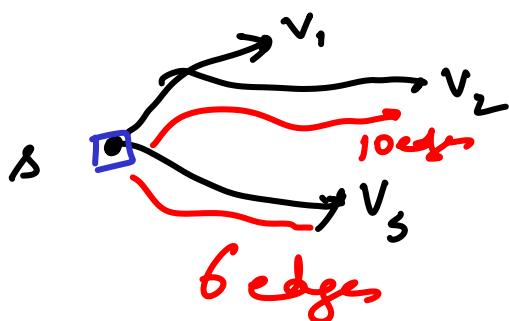
Relax (u, v)

Output the final $D(v)$ for all $v \in V$

Claim At the end of $(V1-1)$ iterations
 $D(v) = \delta(s, v)$

Note: Running time for $BF \sim O(V1 \cdot |E1|)$
 ↗ iteration cost ↗
 relaxation for all edges

Proof by induction on the # of edges in the shortest path from s to v

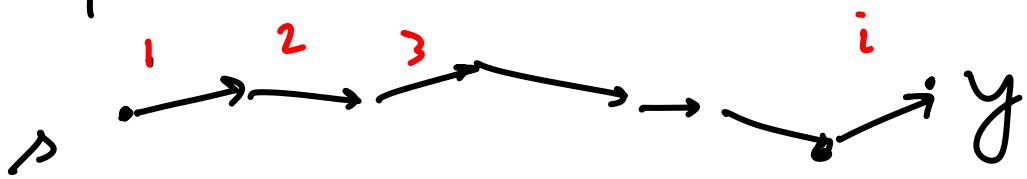


For $\ell = 0$
 $D(s) = 0 = \delta(s, s)$
 So correctly initialized

Suppose it is correct for $< i$ iterations,
 i.e. all vertices x whose short path from s consists of $< i$ edges have $\delta(s, x) = D(x)$
 after $i-1$ iterations

During the i^{th} iteration all edges will undergo relax operation

Consider a vertex y s.t. the shortest path has i edges.



$$D(y) = \delta(s, y) \text{ before the } i^{\text{th}} \text{ iteration}$$

So when we relax edge (y, y)

$$\begin{aligned} \delta(s, y) &\leq D(y) = D(y) + w(y, y) \\ &= \delta(s, y) + w(y, y) \\ &= \delta(s, y) \end{aligned}$$

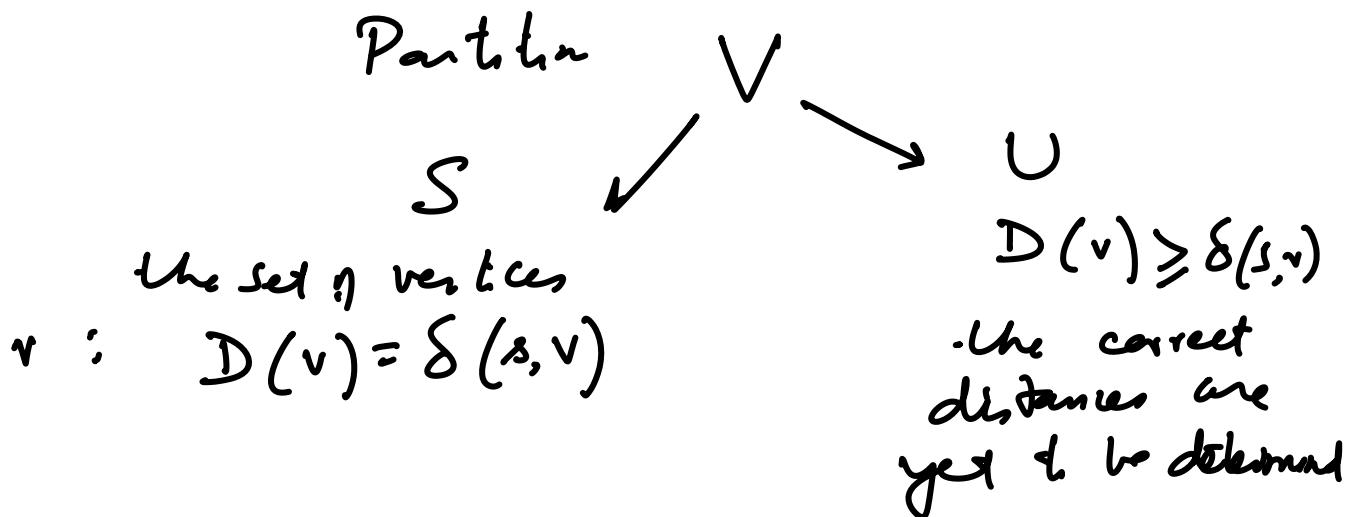
\Rightarrow All vertices have their correct distances

Remark : If there is a -ve cycle in the graph, then BF algorithm can detect it if we let it run for $|V|$ iterations

If there is any change in the D value of a vertex then there must be a negative cycle (shortest cycle must have length $\leq n$)

For non-negative weights we can do better by using Dijkstra

In Dijkstra's algorithm, -the relax operations are carefully scheduled so that all edges are relaxed at most once



Initially $S = \{s\}$ $D(s) = \delta(s, s) = 0$
 Relax all edges (s, v)
 Repeat until $U = \emptyset$

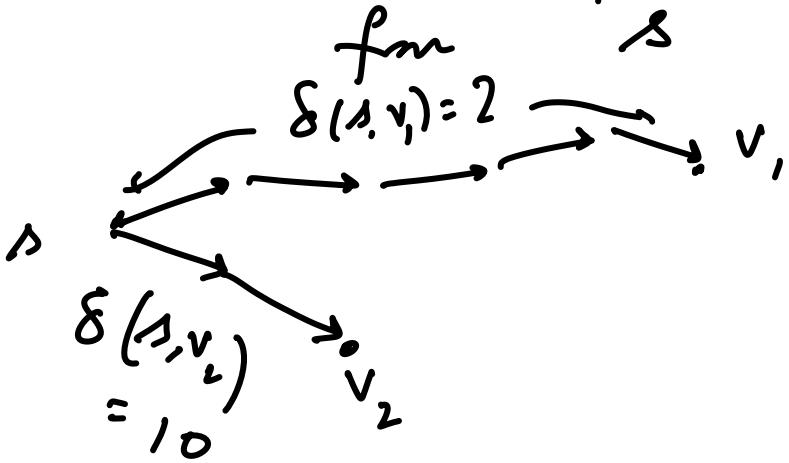
* iterations
 $V-1$

- 1. Choose the vertex with smallest label in U , say x $O(\log V)$ priority que
- 2. Relax all outgoing edges from x
 - Move x from U to S
 - outdegree (x)

$$\begin{aligned} \text{Total time} &= \sum_v \log|V| + \text{outdegree}(v) \\ &\leq O(|V| \log V + |E|) \end{aligned}$$

Why does Dijkstra's algorithm output
the correct distances?

Claim: The algorithm discovers the
shortest path distances in
order of their actual distance
from s

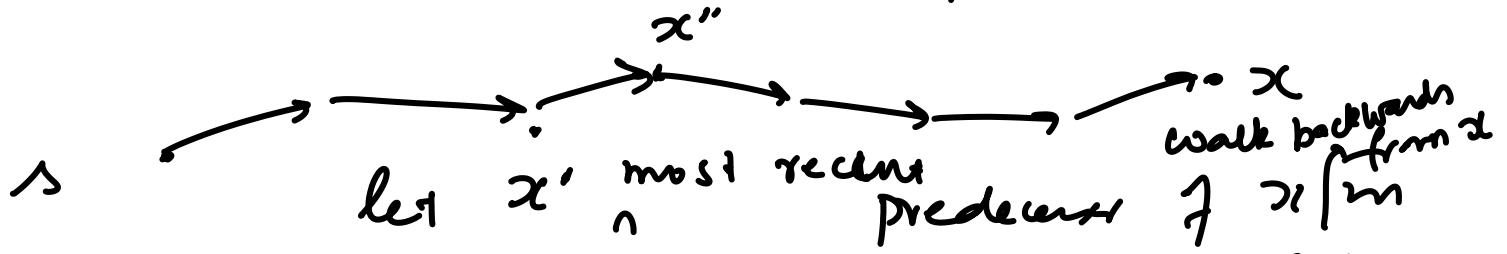


v_1 will move
into S before v_2
in Dijkstra
(and the reverse for
B.F.)

When a vertex x has the smallest
 $D(x)$ in U then $D(x) = \delta(s, x)$

Proof by contradiction : Suppose not, i.e.
 $D(x) > \delta(s, x)$

Consider the shortest paths from $s \rightarrow x$



- The path - that has $D(x') = \delta(s, x')$, and $x' \in S$

Then (x', x'') must have been relaxed when x' moved to S

$$D(x'') \stackrel{?}{=} D(x)$$

\leftarrow because of non-negative weights

So x'' should have been picked