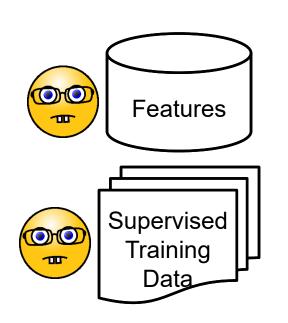
An Intro to Deep Learning for NLP

Mausam

(several slides by Yoav Goldberg, Graham Neubig)

NLP before DL #1





Assumptions

- doc: bag/sequence/tree of words
- model: bag of features (linear)
- feature: symbolic (diff wt for each)

Model (NB, SVM, CRF)



Optimize function (LL, sqd error, margin...)



Learn feature weights

NLP before DL #2

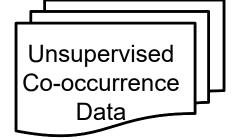




Assumptions

- doc/query/word is a vector of numbers
- dot product can compute similarity
 - via distributional hypothesis

Model (MF, LSA, IR)

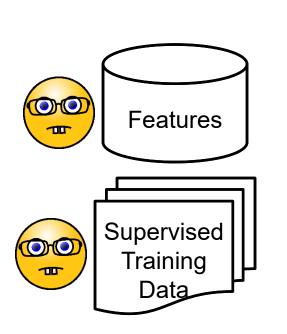




Optimize function (LL, sqd error, margin...)



Learn vectors





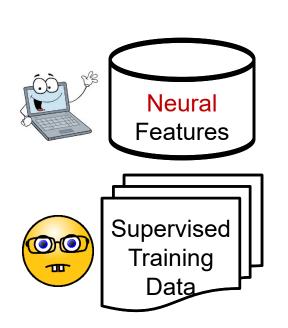
Model (NB, SVM, CRF)



Optimize function (LL, sqd error, margin...)



Learn feature weights





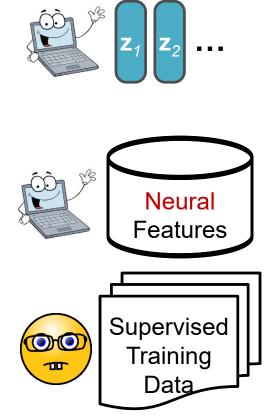
Model (NB, SVM, CRF)



Optimize function (LL, sqd error, margin...)



Learn feature weights





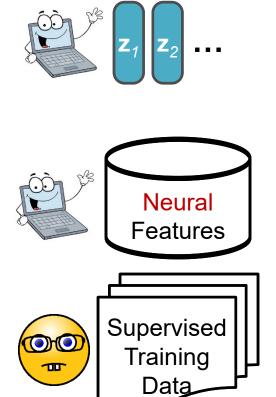
Model (NB, SVM, CRF)



Optimize function (LL, sqd error, margin...)



Learn feature weights+vectors





Model
NN= (NB, SVM, CRF, +++
+ feature discovery)

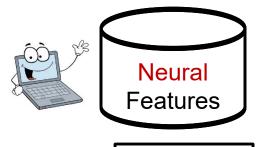


Optimize function (LL, sqd error, margin...)



Learn feature weights+vectors









- doc/query/word is a vector of numbers
- doc: bag/sequence/tree of words
- feature: neural (weights are shared)
- model: bag/seq of features (non-linear)



Model

NN= (NB, SVM, CRF, +++

+ feature discovery)



Optimize function (LL, sqd error, margin...)



Learn feature weights+vectors

Meta-thoughts

Features

- Learned
- in a task specific end2end way
- not limited by human creativity

Everything is a "Point"

- Word embedding
- Phrase embedding
- Sentence embedding
- Word embedding in context of sentence
- Etc

Points are good → reduce sparsity by wt sharing a single (complex) model can handle all pts

Universal Representations

- Non-linearities
 - Allow complex functions

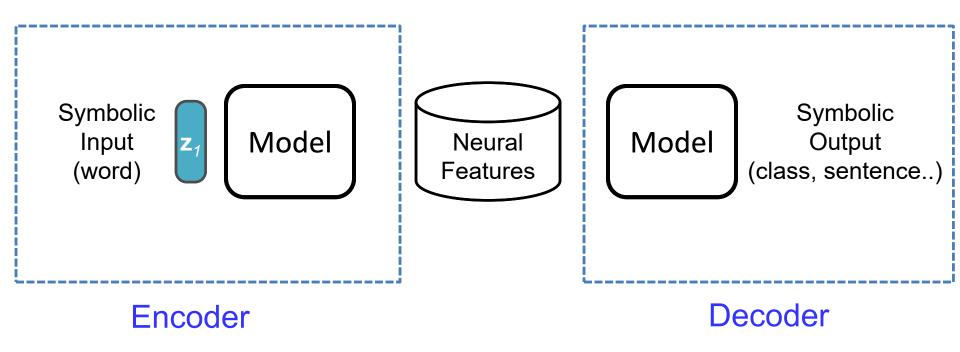
- Put anything computable in the loss function
 - Any additional insight about data/external knowledge

Make symbolic operations continuous

- Symbolic → continuous
 - Yes/No \rightarrow (number between 0 and 1)
 - Good/bad \rightarrow (number between -1 and 1)

- Either remember or forget → partially remember
- Select from n things → weighted avg over n things

Encoder-Decoder



Different assumptions on data create different architectures

- A single vector for an ordered pair of vectors?
- A single vector for a variable-sized bag of vectors?
- Project a vector to a new space?
- Are two vectors (from same space) similar?
- Are two vectors (from different space) similar?
- A new vector that depends on some vector input?

- A single vector for an ordered pair of vectors?
 x;y
- A single vector for a variable-sized bag of vectors? $\sum_i \chi_i$
- Project a vector to a new space?
 Wx
- Are two vectors (from same space) similar?
 x.y
- Are two vectors (from different space) similar?
 xWy
- A new vector that depends on some vector input?
 g(Wx+b)

- Output a probability
- Output one of two classes
- Output one of many classes
- A feature w/ positive & negative influence
- A feature w/ positive influence for "deep" nets

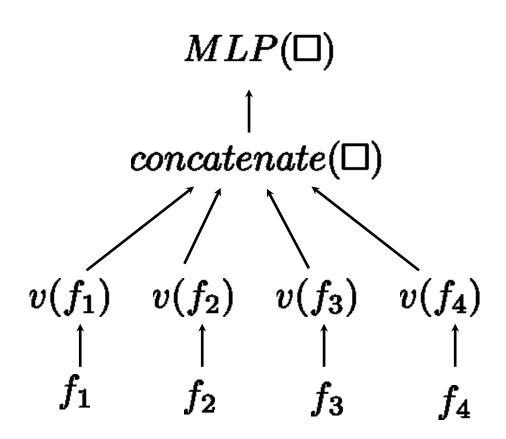
- Output a probability
- Output one of two classes
- Output one of many classes
 softmax
- A feature w/ positive & negative influence
 tanh
- A feature w/ positive influence for "deep" nets
 ReLu

Building Blocks

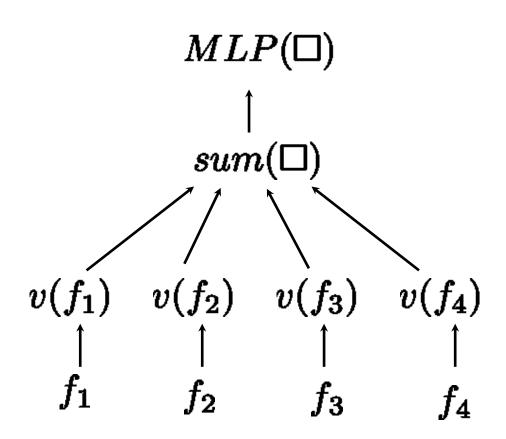
+ ; .

Matrix-mult gate non-linearity

X;Y



X+y



Concat vs. Sum

 Concatenating feature vectors: the "roles" of each vector is retained.

$$concat\left(v("the"),v("thirsty"),v("dog")
ight)$$

prev current next word word word

- Different features can have vectors of different dim.
- Fixed number of features in each example (need to feed into a fixed dim layer).

Concat vs. Sum

• Summing feature vectors: "bag of features"

$$sum\left(v("the"),v("thirsty"),v("dog")
ight)$$
 word word word

- Different feature vectors should have same dim.
- Can encode a bag of arbitrary number of features.

X.y

- degree of closeness
- alignment

- Uses
 - question aligns with answer //QA
 - sentence aligns with sentence //paraphrase
 - word aligns with (~important for) sentence //attention

g(Ax+b)

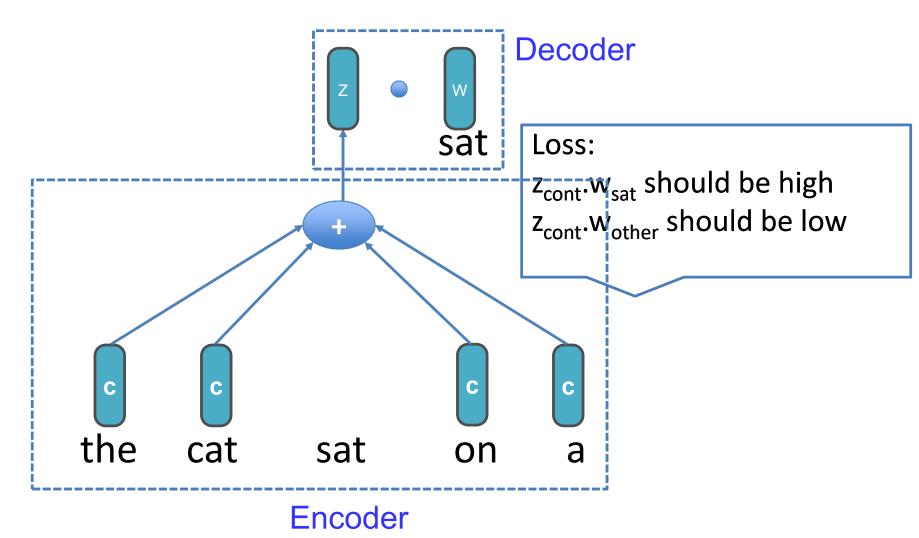
- 1-layer MLP
- Take x
 - project it into a different space //relevant to task
 - add some scalar bias (only increases/decreases it)
 - convert into a required output

- 2-layer MLP
 - Common way to convert input to output

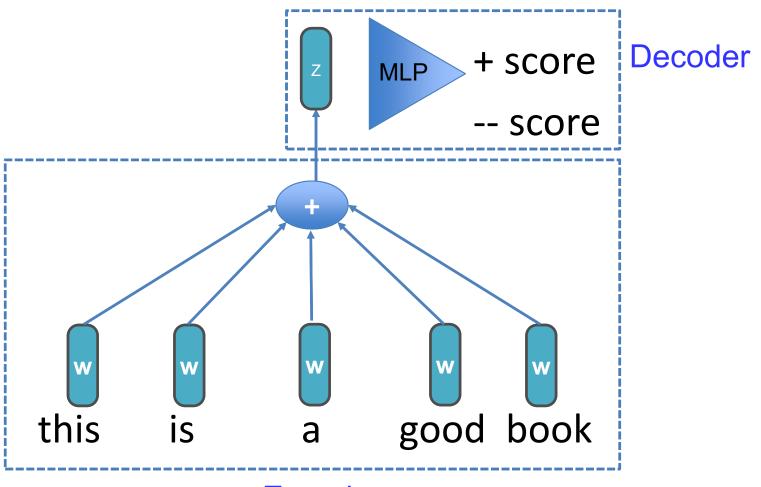
Encoding Architectures

BoW
Bag(N-grams)
Complete History
Complete History & Future

Word2Vec: Bag of (Context) Words



Very Simple Text Classification



Encoder

Importance of Ngrams

- We did '+' bec sentences are variable length
 - Ignored order

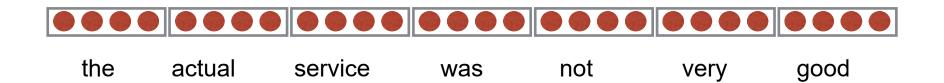
- While we can ignore global order in many cases...
- ... local ordering is still often very important.
- Local sub-sequences encode useful structures.

(so why not just assign a vector to each ngram?)

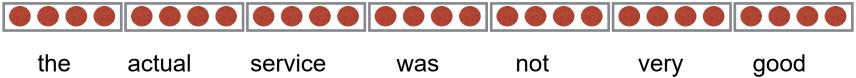
CNN: Convolutional Neural Nets

- bag of n-grams encoding
- feature extractor
 - finds whether/how much feature is present

- Instead of sum uses max
 - Indicates presence instead of strength
 - Also called "Max Pooling"







П



dot



the actual service was not very good

the actual

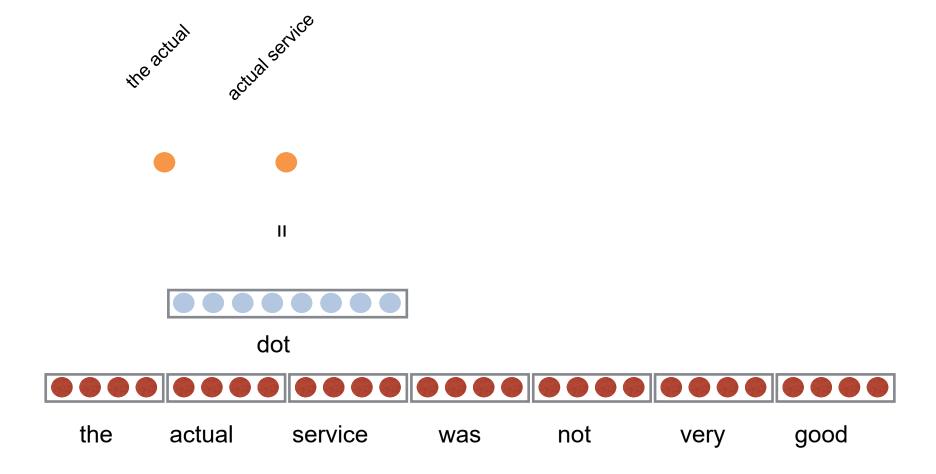
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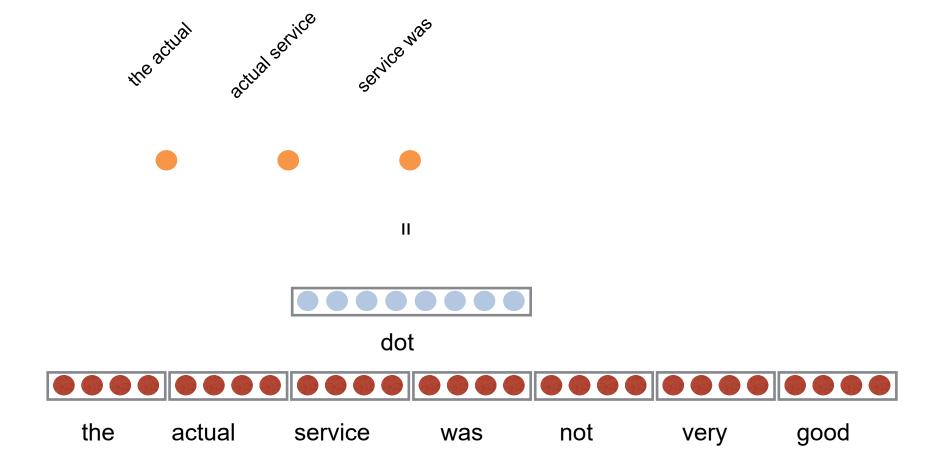


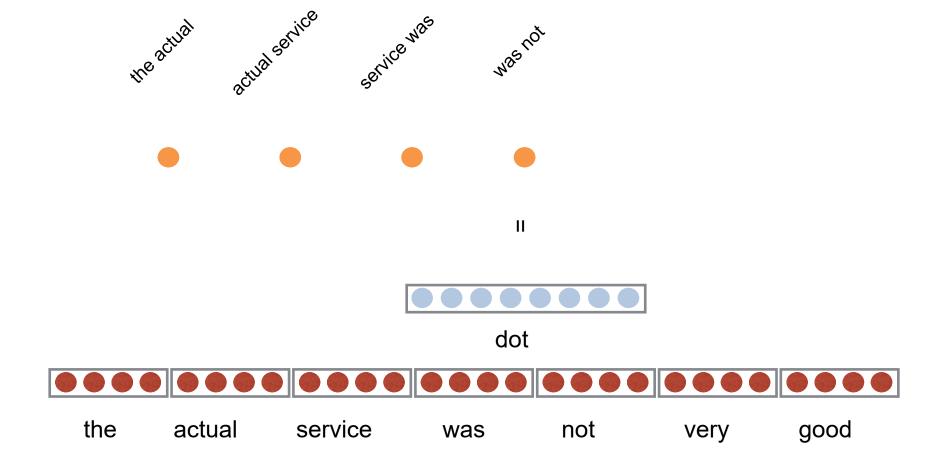
dot

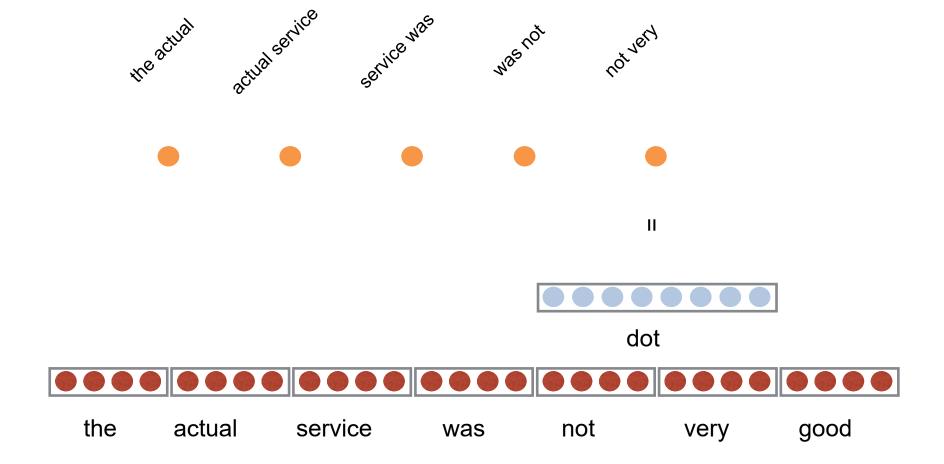


the actual service was not very good











the actual

П



dot



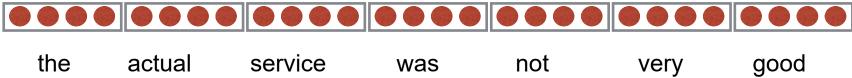
the actual service was not very good



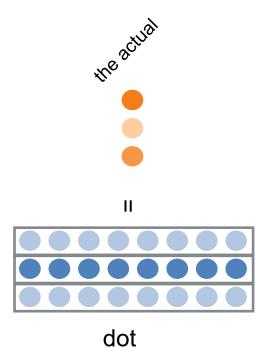
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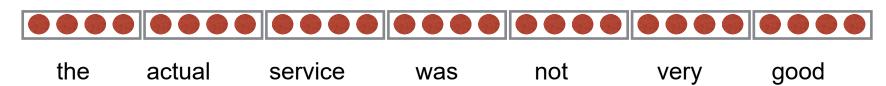


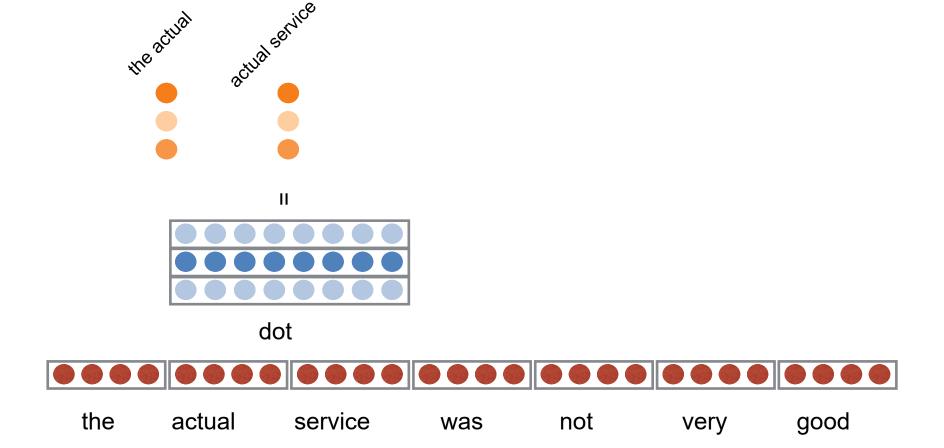
dot

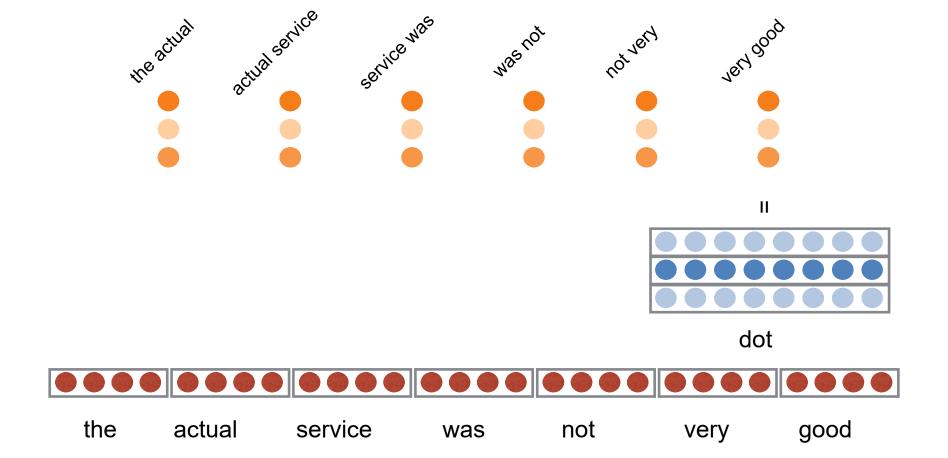


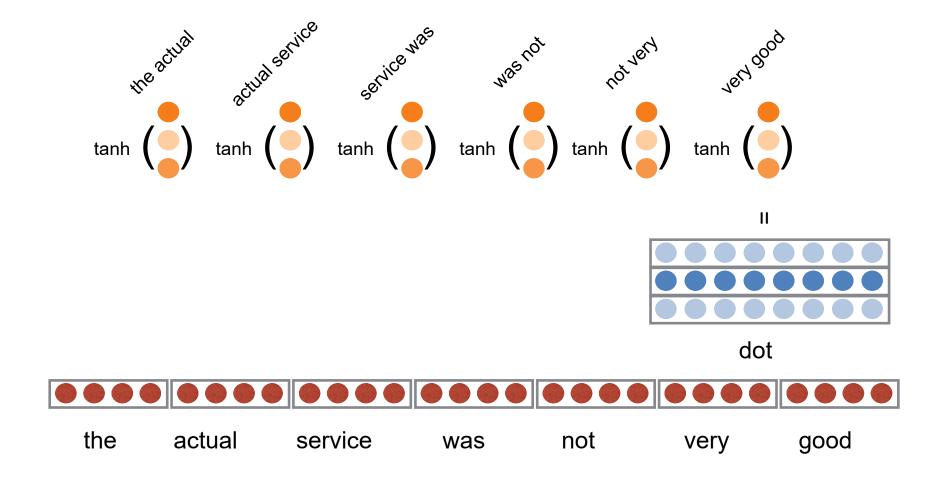
actual service not was very



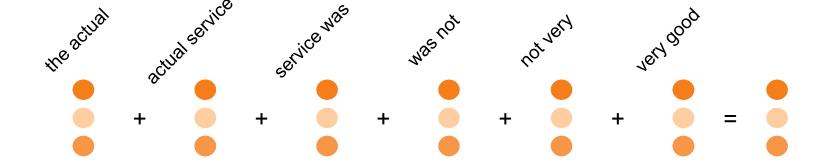


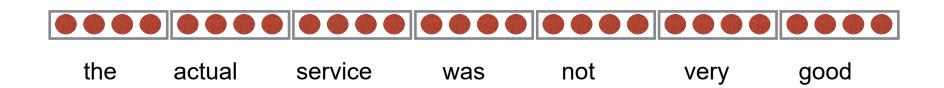




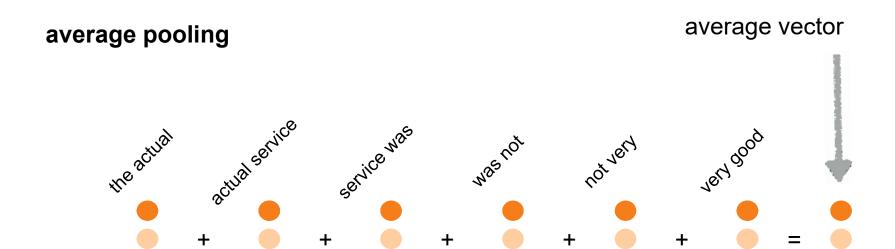


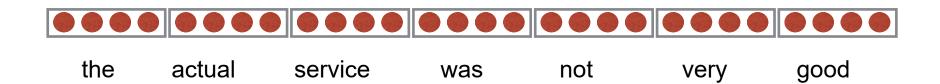
(usually also add non linearity)

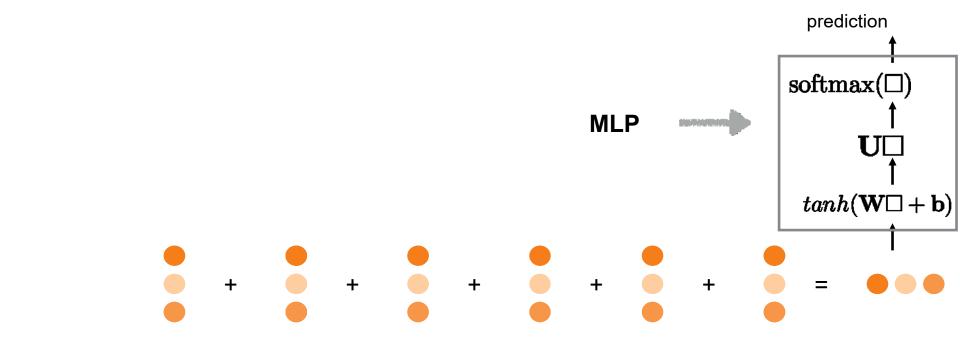


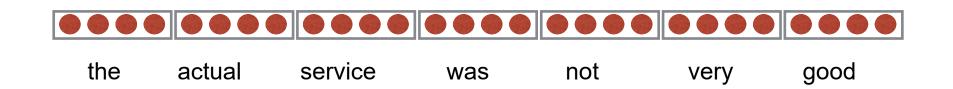


can do "pooling"



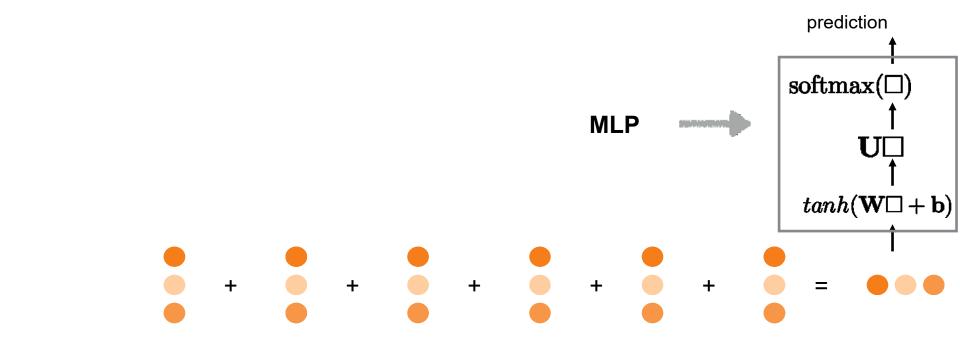


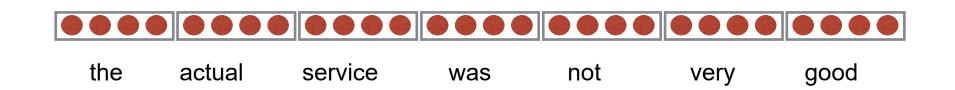




train end-to-end for some task

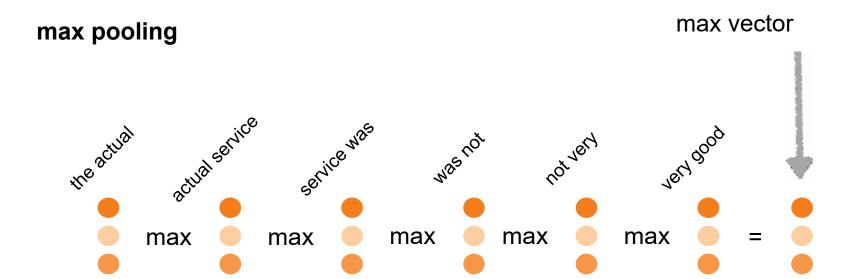
(train the MLP, the filter matrix, and the embeddings together)

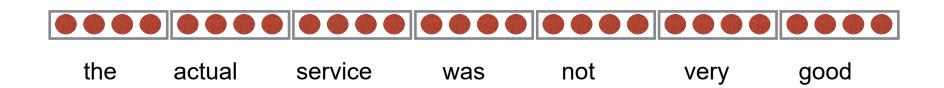




train end-to-end for some task

(train the MLP, the filter matrix, and the embeddings together) the vectors learn to capture what's important





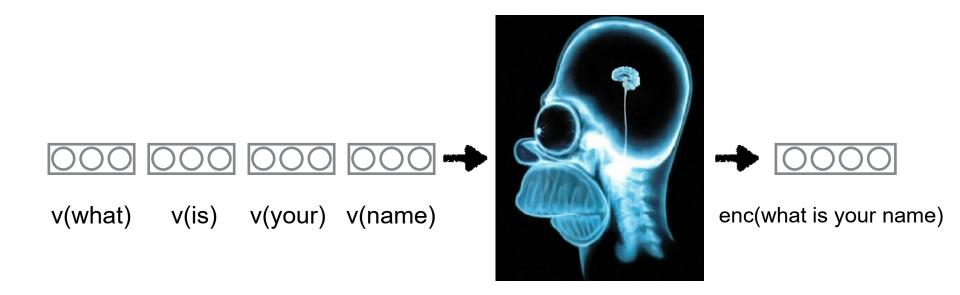
(max in each coordinate)

$CNNs \rightarrow RNNs$

CNNs consider local word order

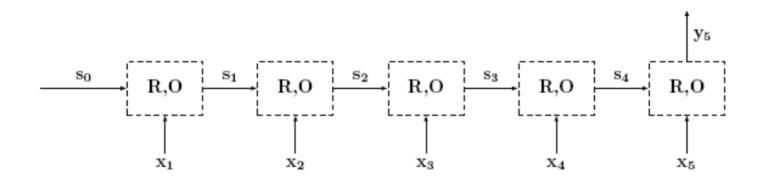
How can we consider **global** word order?

Recurrent Neural Networks



- Very strong models of sequential data.
- Trainable function from n vectors to a single vector.

Recurrent Neural Networks



Simple RNN (Elman RNN)

$$R_{SRNN}(\mathbf{s_{i-1}}, \mathbf{x_i}) = tanh(\mathbf{W^s} \cdot \mathbf{s_{i-1}} + \mathbf{W^x} \cdot \mathbf{x_i})$$

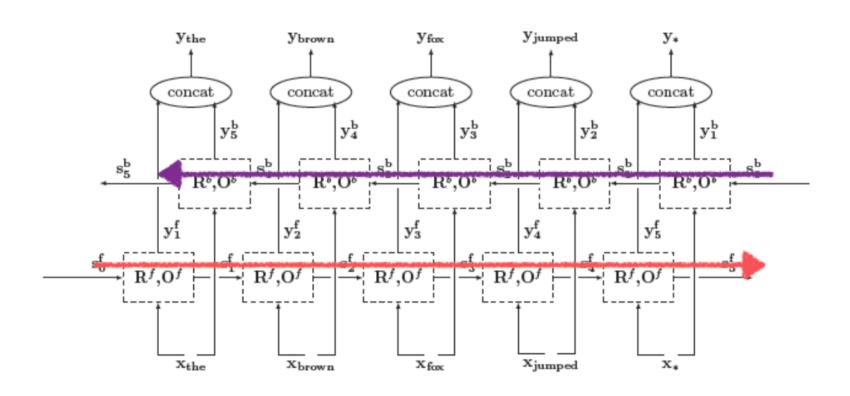
In principle: capture infinite history upto this point

In practice: have issues with long sequences

RNN -> LSTM

Good for backpropagating through long chain sequences

Bi-directional RNN

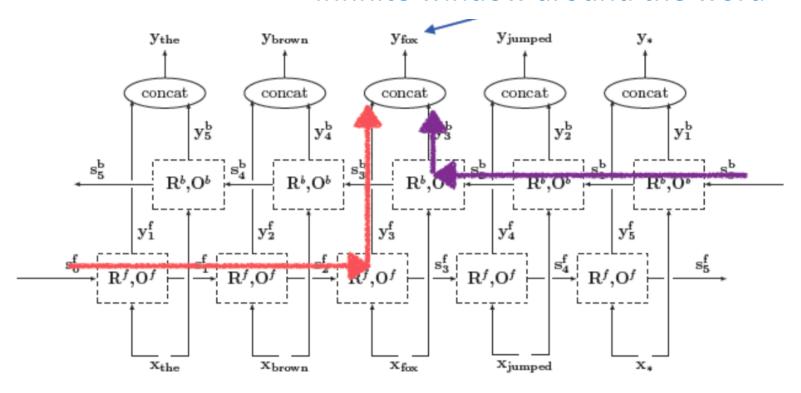


One RNN runs left to right.

Another runs right to left.

Encode both future and history of a word.

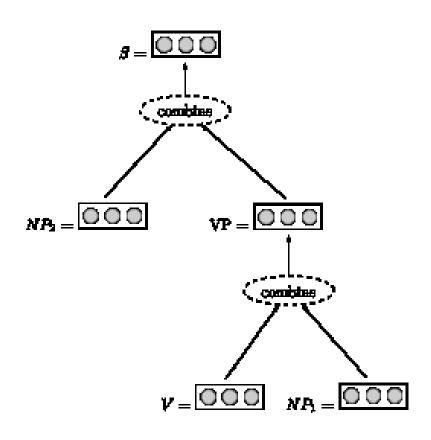
Infinite window around the word

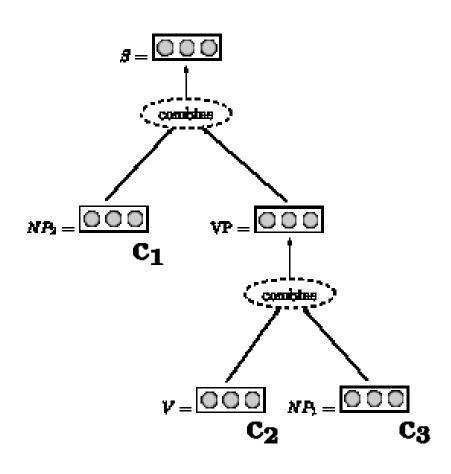


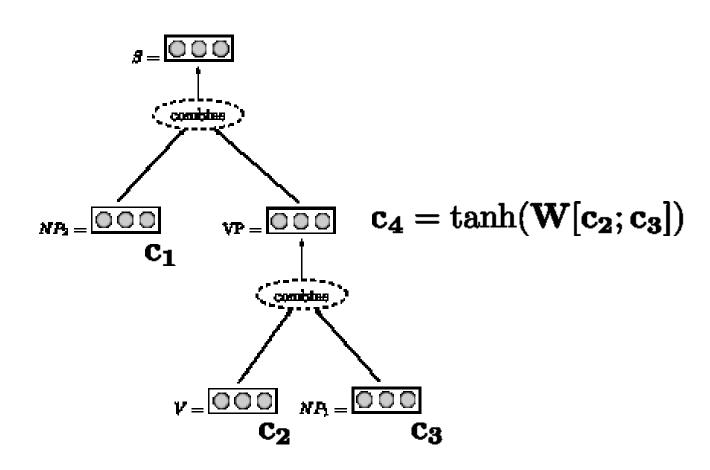
One RNN runs left to right.

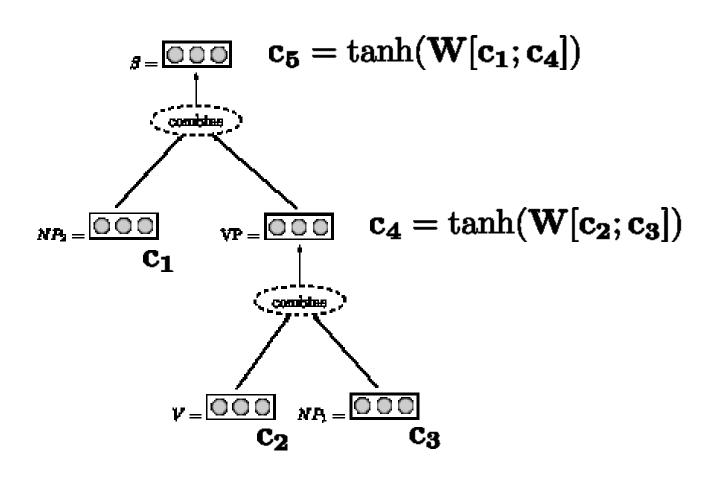
Another runs right to left.

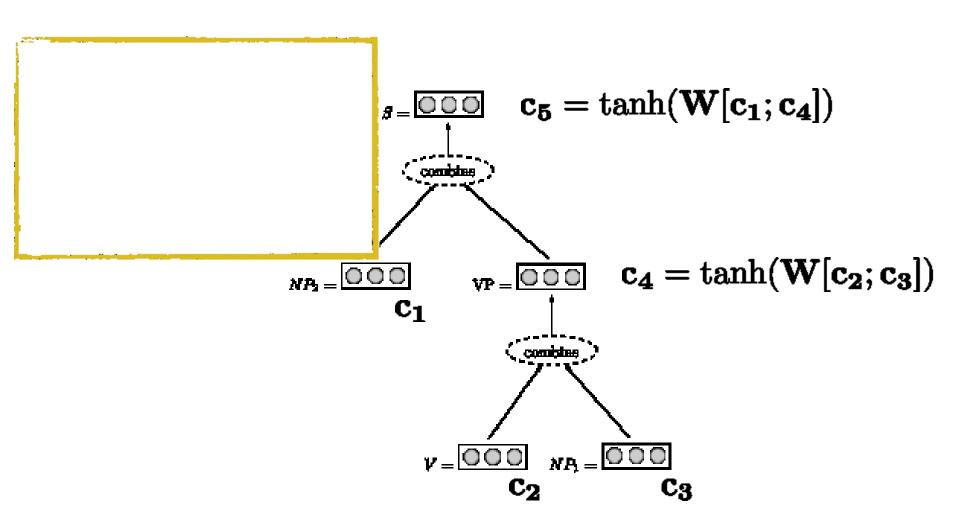
Encode both future and history of a word.







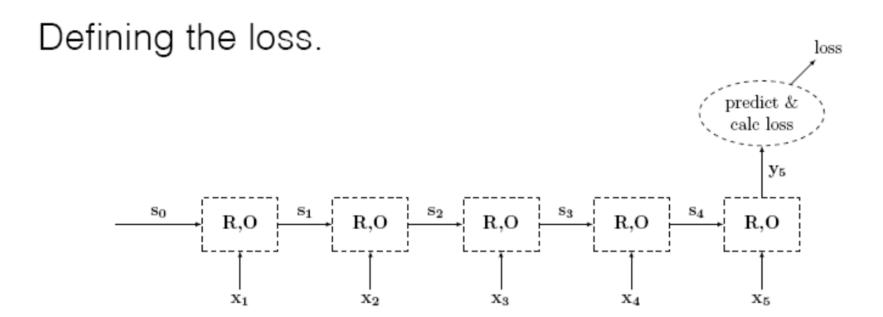




Decoding Architectures

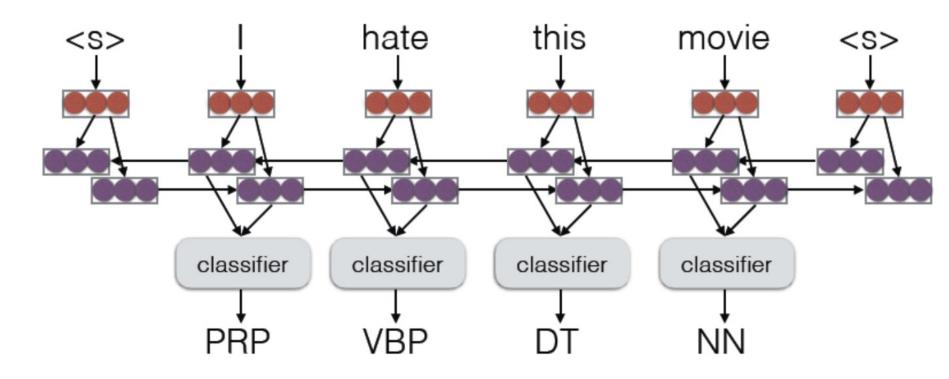
Acceptor
Transducer
Language Model

RNN Acceptor

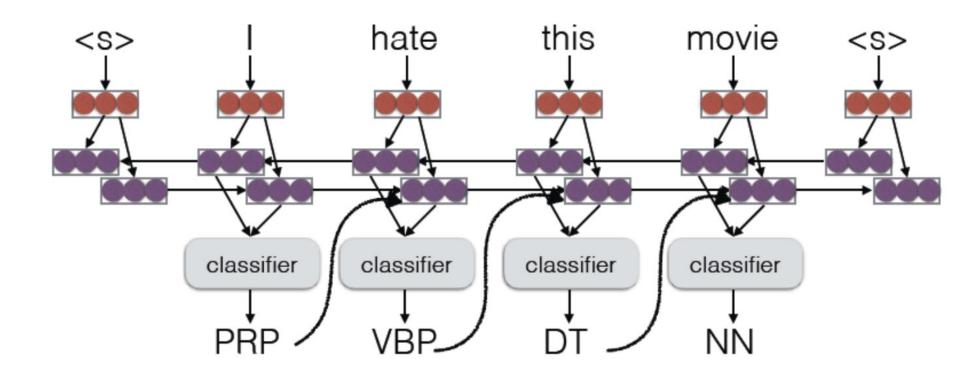


Acceptor: predict something from end state. Backprop the error all the way back. Train the network to capture meaningful information

Sequence Labeling with Transducer BiLSTM



A Tagger Considering Output Structure



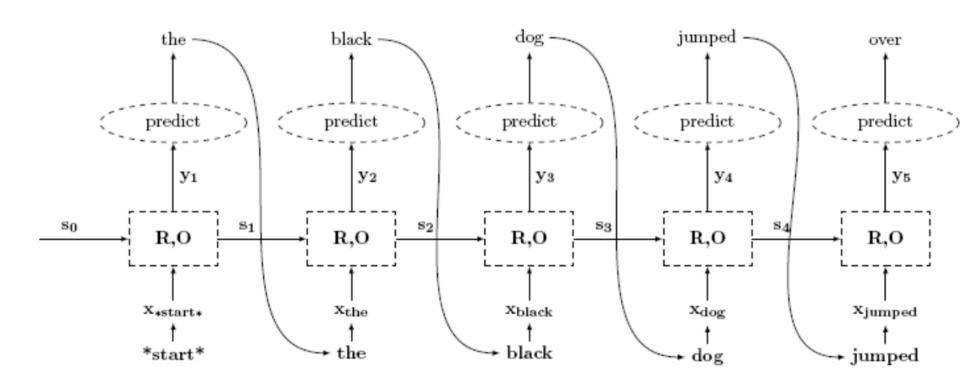
Aside

How about an architecture for **0 to n** mapping.

(Neural Language Model)

RNN Language Models

- Training: similar to an RNN Transducer.
- *Generation*: the output of step i is input to step i+1.



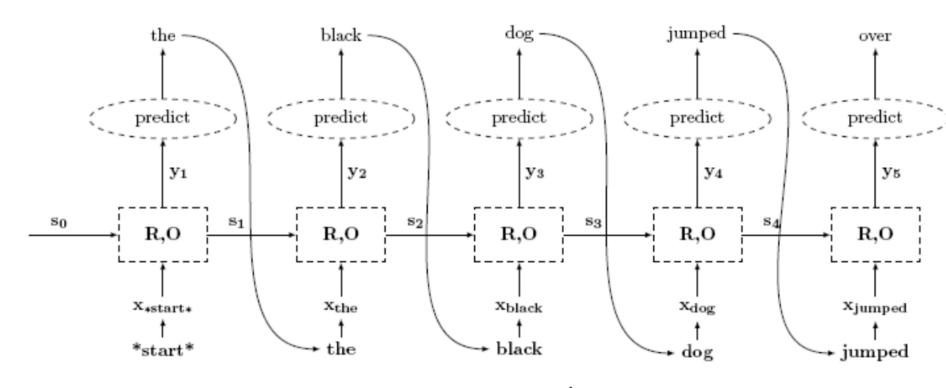
RNN Language Model for generation

 Define the probability distribution over the next item in a sequence (and hence the probability of a sequence).

$$P(w_{1:n}) = P(w_1)P(w_2 \mid w_1)P(w_3 \mid w_{1:2})P(w_4 \mid w_{1:3}) \dots P(w_n \mid w_{1:n-1})$$

$$P(w_1,...,w_n) = \prod_{i=1}^n P(t_i = w_i | w_1,...,w_{i-1})$$

RNN Language Models

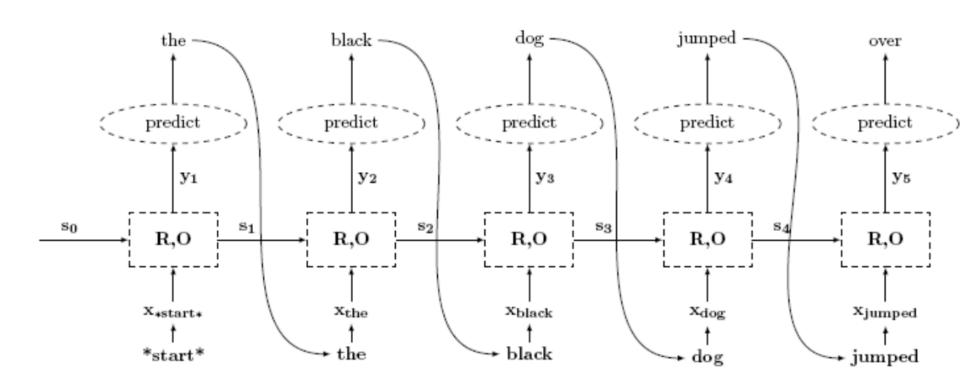


$$p(t_{j+1} = k \mid \hat{t}_{1:j}) = f(\text{RNN}(\hat{\mathbf{t}}_{1:j}))$$
$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1})$$

$$\begin{aligned} p(t_{j+1} = k \mid \hat{t}_{1:j}) &= f(O(\mathbf{s_{j+1}})) \\ \mathbf{s_{j+1}} &= R(\hat{\mathbf{t_j}}, \mathbf{s_j}) \\ \hat{t}_j &\sim p(t_j \mid \hat{t}_{1:j-1}) \end{aligned}$$

RNN Language Models

• *Generation*: the output of step i is input to step i+1.



Back to Original question

How about an architecture for **m to n** mapping.

Generating sentences is nice, but what if we want to add some additional conditioning contexts?

Conditioned Language Model

 Not just generate text, generate text according to some specification

<u>Input X</u>

Structured Data

English

Document

Utterance

Image

Speech

Output Y (Text)

NL Description

Japanese

Short Description

Response

Text

Transcript

<u>Task</u>

NL Generation

Translation

Summarization

Response Generation

Image Captioning

Speech Recognition

RNN Language Model for Conditioned generation

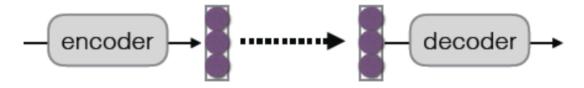
Let's add the condition variable to the equation.

$$P(\top) = \prod_{i=1}^{I} P(t_i | t_1, ..., t_{i-1})$$
Next Word Context

$$P(T|C) =$$

How to Pass Context

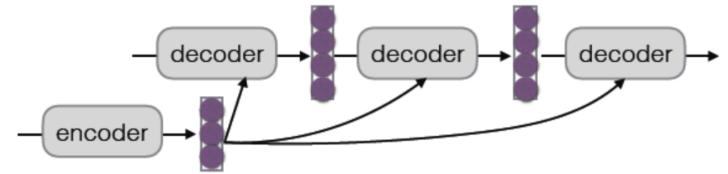
Initialize decoder w/ encoder (Sutskever et al. 2014)



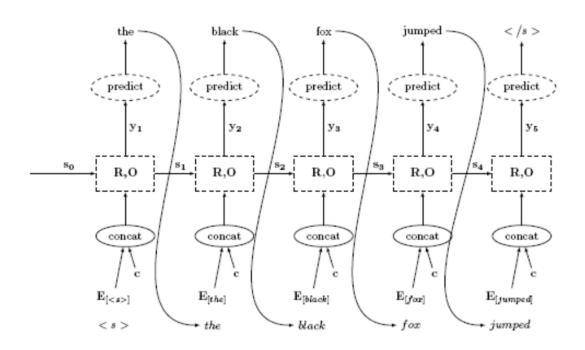
Transform (can be different dimensions)



Input at every time step (Kalchbrenner & Blunsom 2013)



RNN Language Model for Conditioned generation



$$p(t_{j+1} = k \mid \hat{t}_{1:j}, c) = f(O(\mathbf{s_{j+1}}))$$
$$\mathbf{s_{j+1}} = R(\mathbf{s_j}, [\hat{\mathbf{t}_j}; \mathbf{c}])$$
$$\hat{t}_j \sim p(t_i \mid \hat{t}_{1:j-1}, c)$$

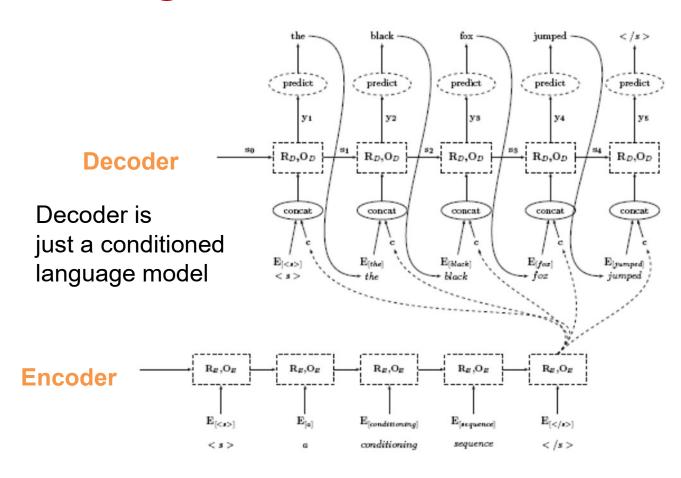
RNN Language Model for Conditioned generation

what if we want to condition on an entire sentence?

just encode it as a vector...

$$\mathbf{c} = \mathrm{RNN^{enc}}(\mathbf{x_{1:n}})$$

This is also called "Encoder Decoder" architecture.



The Generation Problem

We have a probability model, how do we use it to generate a sentence?

Two methods:

- **Sampling:** Try to generate a *random* sentence according to the probability distribution.
- Argmax: Try to generate the sentence with the highest probability.

Ancestral Sampling

Randomly generate words one-by-one.

while
$$y_{j-1} != "": $y_j \sim P(y_j \mid X, y_1, ..., y_{j-1})$$$

An **exact method** for sampling from P(X), no further work needed.

Greedy Search

One by one, pick the single highest-probability word

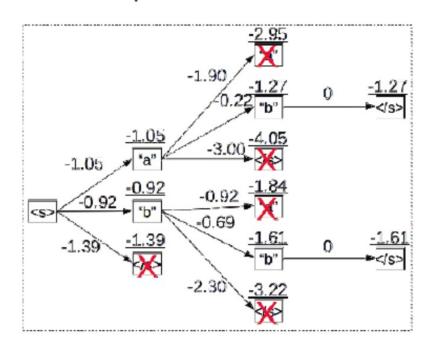
while
$$y_{j-1} != "": $y_j = argmax P(y_j | X, y_1, ..., y_{j-1})$$$

Not exact, real problems:

- · Will often generate the "easy" words first
- Will prefer multiple common words to one rare word

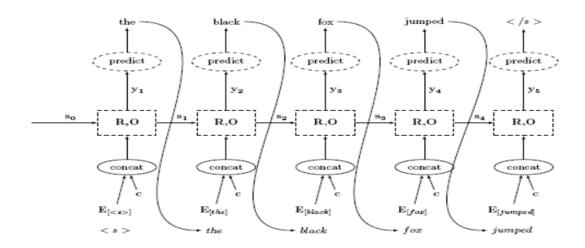
Beam Search

Instead of picking one high-probability word, maintain several paths



How to Train this Model?

- Issues with vanilla training
 - Slow convergence. Model instability. Poor skill.
- Simple idea: Teacher Forcing
 - Just feed in the correct previous word during training
- Drawback: Exposure bias
 - Not exposed to mistakes during training



Solutions to Exposure Bias

- Start with no mistakes, and then
 - gradually introduce them using annealing

- Dropout inputs
 - Helps ensure that the model doesn't rely too heavily on predictions, while still using them

Corrupt training data

Sequence 2 Sequence

Part II: with attention

Sentence Representation

You can't cram the meaning of a whole %&!\$# sentence into a single \$&!#* vector!



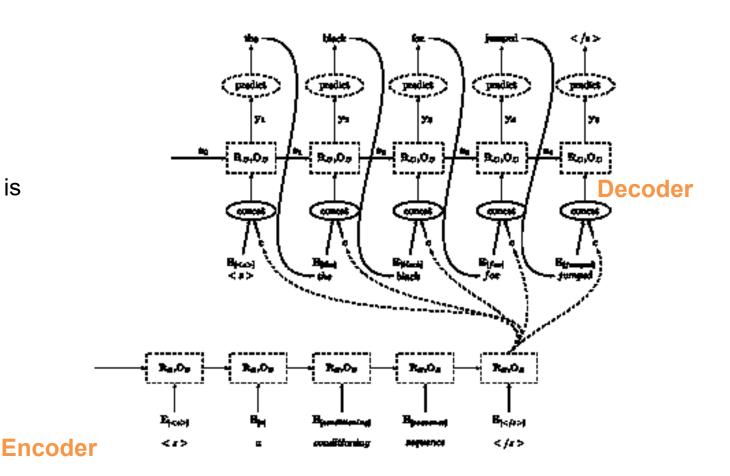
But what if we could use multiple vectors, based on the length of the sentence.

this is an example -----

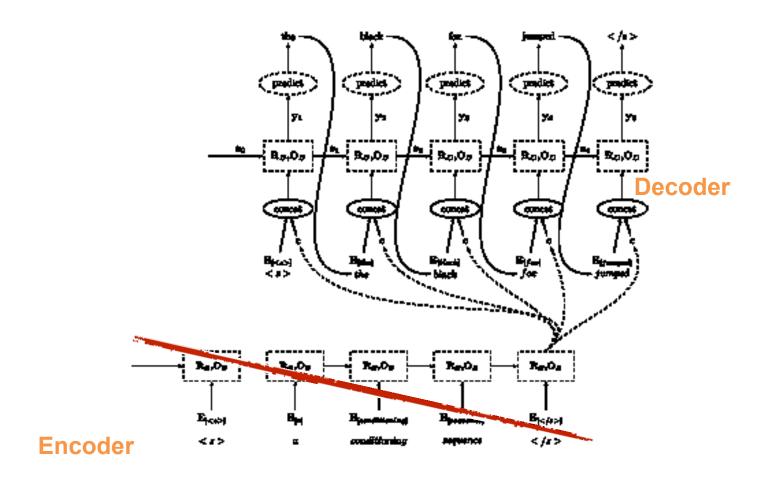
this is an example -----

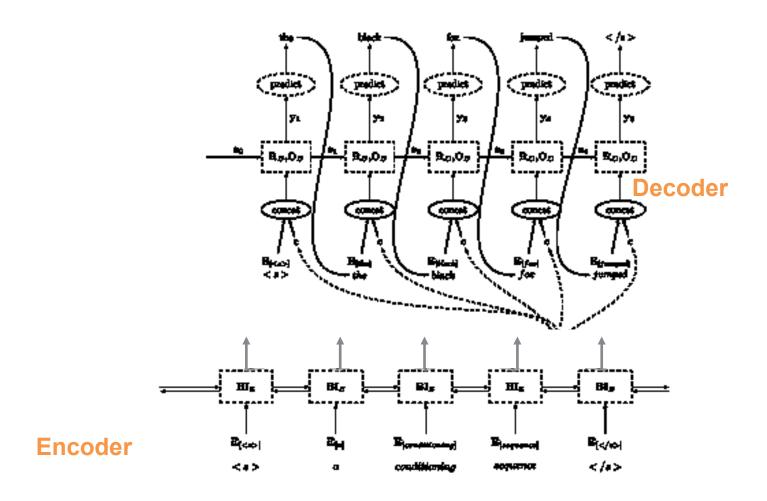


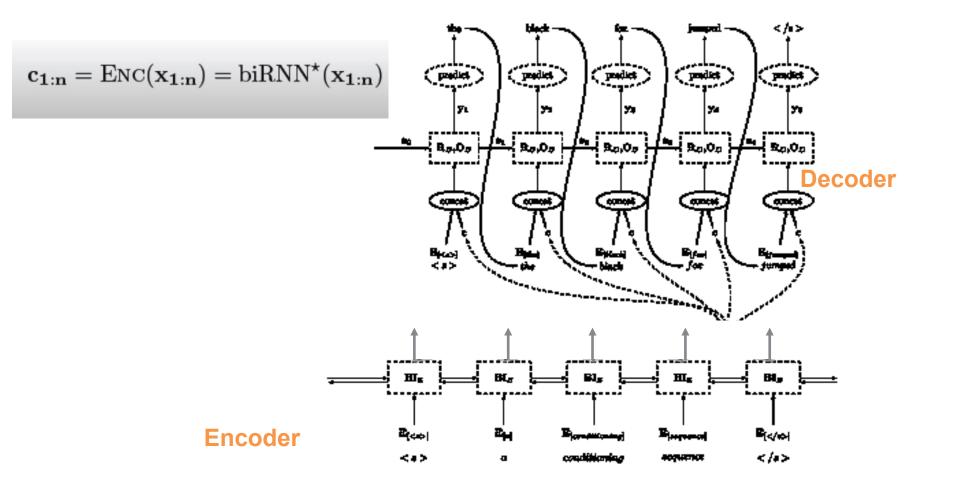
main idea:
encoding
a single vector is
too restrictive.

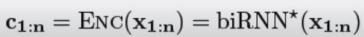


 Instead of the encoder producing a single vector for the sentence, it will produce a one vector for each word.

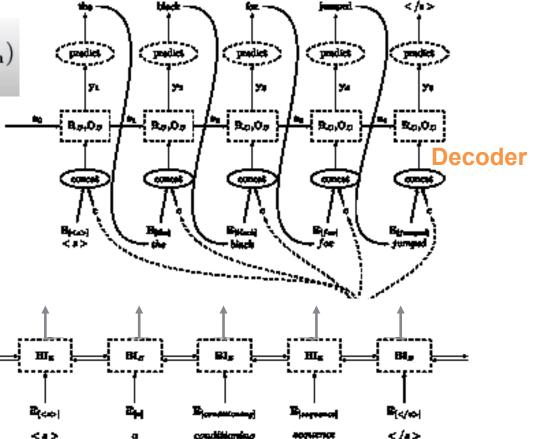






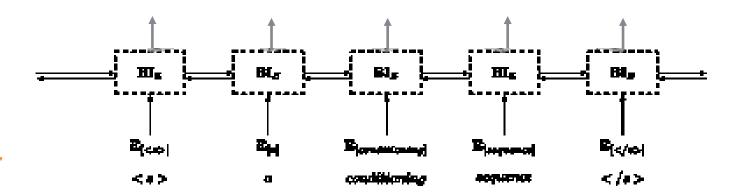


but how do we feed this sequence to the decoder?



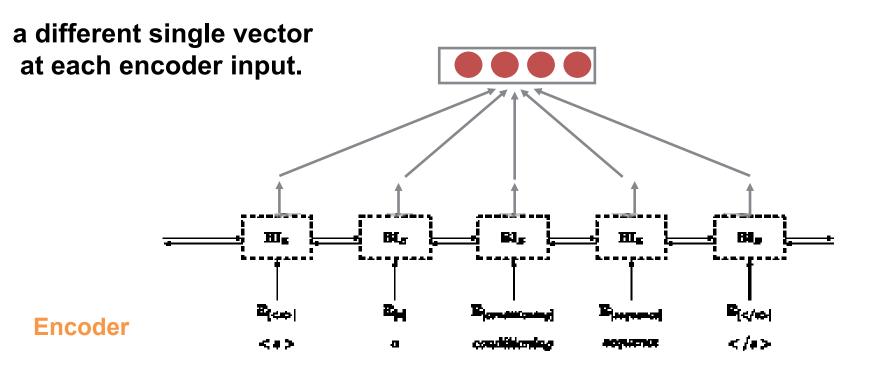
Encoder

we can combine the different outputs into a single vector (attended summary)



Encoder

we can combine the different outputs into a single vector (attended summary)



$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x_{1:n}}) = f(O(\mathbf{s_{j+1}}))$$

$$\mathbf{s_{j+1}} = R(\mathbf{s_j}, [\hat{\mathbf{t_j}}])$$

$$= \operatorname{attend}(\mathbf{c_{1:n}}, \hat{t}_{1:j})$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1}, \mathbf{x_{1:n}})$$

$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O(\mathbf{s_{j+1}}))$$

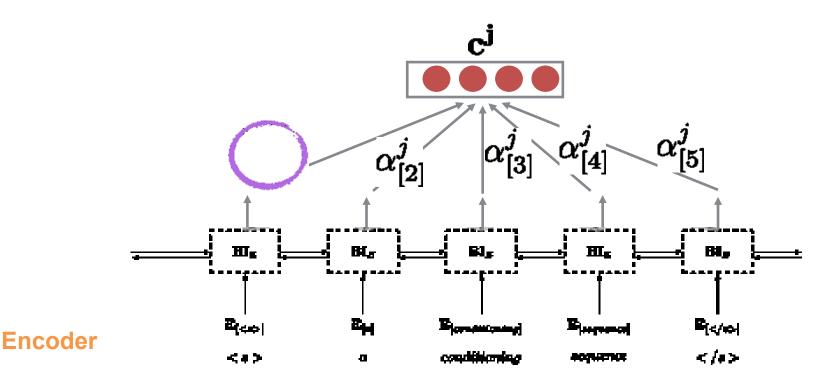
$$\mathbf{s_{j+1}} = R(\mathbf{s_{j}}, [\hat{\mathbf{t}_{j}}; \mathbf{c^{j}}])$$

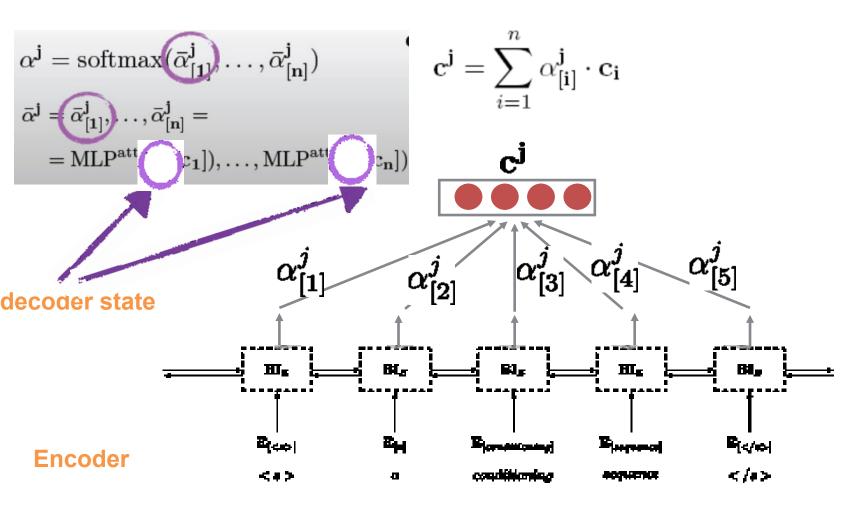
$$\hat{t}_{j} \sim p(t \mid |\hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$\mathbf{c^{j}} = \sum_{i=1}^{n} \alpha_{[i]}^{j} \cdot \mathbf{c_{i}}$$

$$\alpha^{\mathbf{j}} = \operatorname{softmax}(\bar{\alpha}^{\mathbf{j}}_{[\mathbf{1}]}, \dots, \bar{\alpha}^{\mathbf{j}}_{[\mathbf{n}]})$$

$$\mathbf{c^j} = \sum_{i=1}^n \mathbf{c_i}$$





$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O_{\text{dec}}(\mathbf{s}_{j+1}))$$

$$\mathbf{s}_{j+1} = R_{\text{dec}}(\mathbf{s}_{j}, [\hat{\mathbf{t}}_{j}; \mathbf{c}^{j}])$$

$$\mathbf{c}^{j} = \sum_{i=1}^{n} \alpha_{[i]}^{j} \cdot \mathbf{c}_{i}$$

$$\mathbf{c}_{1:n} = \text{biRNN}_{\text{enc}}^{\star}(\mathbf{x}_{1:n})$$

$$\alpha^{j} = \text{softmax}(\bar{\alpha}_{[1]}^{j}, \dots, \bar{\alpha}_{[n]}^{j})$$

$$\bar{\alpha}_{[i]}^{j} = \text{MLP}^{\text{att}}([\mathbf{s}_{j}; \mathbf{c}_{i}])$$

$$\hat{t}_{j} \sim p(t_{j} \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$f(\mathbf{z}) = \text{softmax}(\text{MLP}^{\text{out}}(\mathbf{z}))$$

$$MLP^{att}([s_j; c_i]) =$$

 $MLP^{att}([s_i; c_i]) =$

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$$\mathbf{s}_{j+1} = R_{\text{dec}}(\mathbf{s}_{j}, [\hat{\mathbf{t}}_{j}; \mathbf{c}^{j}])$$

$$\mathbf{c}^{j} = \sum_{i=1}^{n} \alpha_{[i]}^{j} \cdot \mathbf{c}_{i}$$

$$\mathbf{c}_{1:n} = \text{biRNN}_{\text{enc}}^{\star}(\mathbf{x}_{1:n})$$

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$$\bar{\alpha}_{[i]}^{j} = \text{MLP}^{\text{att}}([\mathbf{s}_{j}; \mathbf{c}_{i}])$$

$$\hat{t}_{j} \sim p(t_{j} \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

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$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O_{\text{dec}}(\mathbf{s}_{j+1}))$$

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$$\mathbf{c}^{j} = \sum_{i=1}^{n} \alpha_{[i]}^{j} \cdot \mathbf{c}_{i}$$

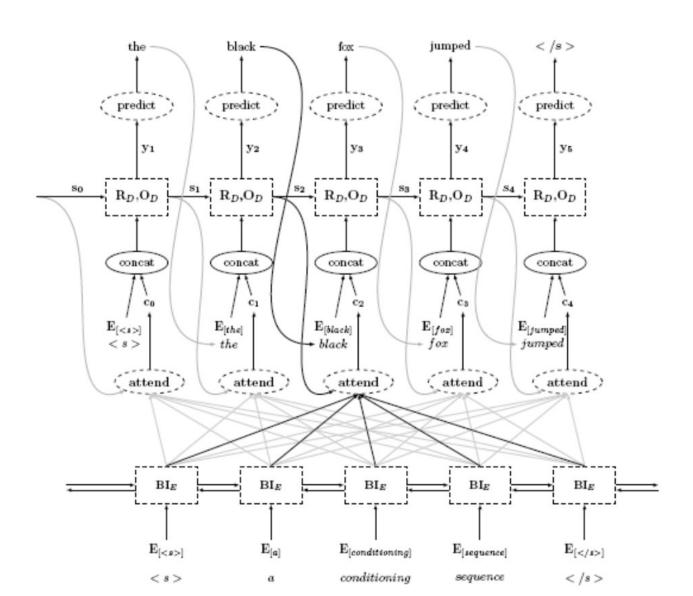
$$\mathbf{c}_{i:n} = \text{biRNN}_{\text{enc}}^{\star}(\mathbf{x}_{1:n})$$

$$\alpha^{j} = \text{softmax}(\bar{\alpha}_{[1]}^{j}, \dots, \bar{\alpha}_{[n]}^{j})$$

$$\bar{\alpha}_{[i]}^{j} = \text{MLP}^{\text{att}}([\mathbf{s}_{j}; \mathbf{c}_{i}])$$

$$\hat{t}_{j} \sim p(t_{j} \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$f(\mathbf{z}) = \text{softmax}(\text{MLP}^{\text{out}}(\mathbf{z}))$$



Encoder encodes a sequence of vectors, c₁,...,c_n

 At each decoding stage, an MLP assigns a relevance score to each Encoder vector.

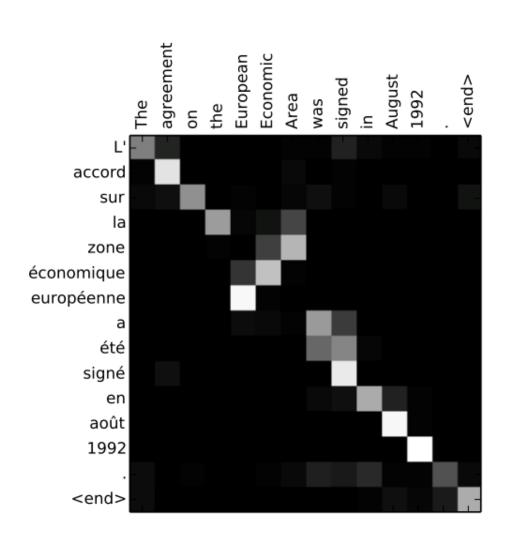
The relevance score is based on c_i and the state s_i

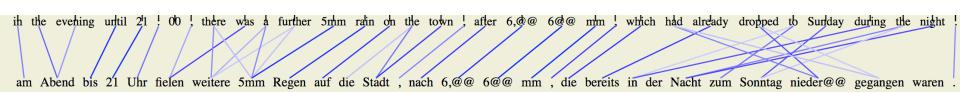
 Weighted-sum (based on relevance) is used to produce the conditioning context for decoder step j.

- Decoder "pays attention" to different parts of the encoded sequence at each stage.
- The attention mechanism is "soft" -- it is a mixture of encoder states.

- The encoder acts as a read-only memory for the decoder
- The decoder chooses what to read at each stage

- Attention is very effective for sequence-to-sequence tasks.
- Current state-of-the-art systems all use attention.
 (this is basically how Machine Translation works)
- Attention makes models somewhat more ~interpretable.
- (we can see where the model is "looking" at each stage of the prediction process)





since then ! the island authorities have tribed to plut ah end to the illegal behaviour of non-@@ alcoholic tourists ih Mag@@ alu@@ ! by minimizing the number of participants ih the notorious alcohol@@ -free bar !

die Insel@@ behä¶rden haben seither versucht , das ordnungs@@ widrige Verhalten alkohol@@ isierter Urlauber in Mag@@ alu@@ f zu stoppen , indem die Anzahl der Teilnehmer an den berä¼chtigten alkohol@@ get@@ rā-nkten Knei@@ pent@@ ouren minimiert wurde

Attention is not Explanation

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Complexity

• Encoder decoder:

• Encoder-decoder with attention:

Complexity

Encoder decoder: O(n+m)

Encoder-decoder with attention: O(nm)

Beyond Seq2Seq

- Can think of a general design pattern in neural nets:
 - Input: sequence, query
 - Encode the input into a sequence of vectors
 - Attend to the encoded vectors, based on query (weighted sum, determined by query)
 - Predict based on the attended vector

Attention Functions

v: attended vec, q: query vec MLPatt(q;v)=

• Additive Attention: $ug(W^1v + W^2q)$

• Dot Product: $\mathbf{v} \cdot \mathbf{q}$

• Bilinear attention: $\mathbf{v}^{\mathsf{T}}\mathbf{W}\mathbf{q}$

Additive vs Multiplicative

While the two are similar in theoretical complexity, dot-product attention is much faster and more space-efficient in practice, since it can be implemented using highly optimized matrix multiplication code.

While for small values of d_k the two mechanisms perform similarly, additive attention outperforms dot product attention without scaling for larger values of d_k [3]. We suspect that for large values of d_k , the dot products grow large in magnitude, pushing the softmax function into regions where it has extremely small gradients ⁴. To counteract this effect, we scale the dot products by $\frac{1}{\sqrt{d_k}}$.

$$rac{{f v}\cdot{f q}}{\sqrt{d_k}}$$

d_k is the dimensionality of q and v

Paper's Justification:

To illustrate why the dot products get large, assume that the components of q and k are independent random variables with mean 0 and variance → Then their dot product, q · k has mean 0 and variance d_k

Key-Value Attention

- Split v into two vectors v=[v_k;v_v]
 - $-v_k$: key vector
 - $-v_v$: value vector

- Use key vector for computing attention $MLP^{att}(q;v) = ug(\mathbf{W}^{1}v_{k} + \mathbf{W}^{2}q) //additive$
- Use value vector for computing attended summary

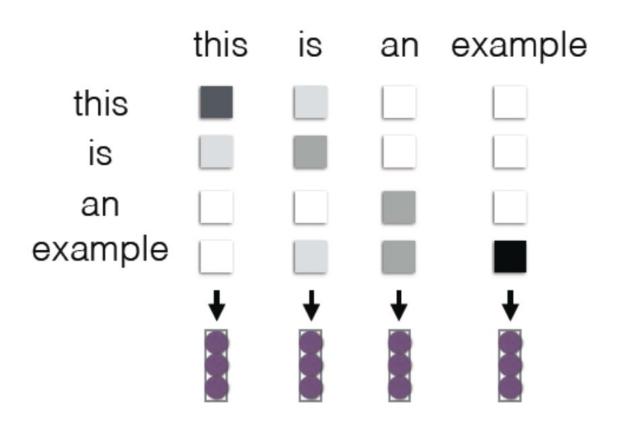
$$\mathbf{v}^{\mathbf{j}} = \sum_{i=1}^{n} \alpha_{[i]}^{\mathbf{j}} \cdot (\mathbf{v}_{\mathbf{v}})_{\mathbf{i}}$$

Multi-head Key-Value Attention

- For each head
 - Learn different projection matrices W_q , W_k , W_v
- MLP^{att}(q;v)= $[(v_k W_k).(qW_q)]/sqrt(d_k)$
- For summary use $v_v W_v$ (instead of v_v)
- Train many such heads and
 - use aggr(all such attended summaries)

Self-attention/Intra-attention

Each element in the sentence attends to other elements → context sensitive encodings!



Do we "need" an LSTM?

They are slow

- Sequential nature of computation makes it tough to optimize operations on GPUs
- Contrast to CNNs: convolutions completely parallelizable

They are not deep

- Vanishing gradient: aggravated for deeper networks
- Less depth

 low compositionality power of the network
- Deepest LSTM networks are 8 layered
 - in-contrast to 50-layered Resnets

They don't transfer well

- Networks trained on one task, do not generalize well to even othe datasets in the same task, not to speak about other tasks
- ImageNet-trained ResNet fine-tuned on many other datasets

Output Probabilities **Transformer** Softmax Linear Add & Norm Feed Forward Add & Norm Add & Norm Multi-Head Feed Attention Forward N× Add & Norm $N \times$ Add & Norm Masked Multi-Head Multi-Head Attention Attention Positional Positional Encoding Encoding Input Output Embedding Embedding Inputs Outputs (shifted right)

Transformer + PreTraining

- In NLP, we are interested in solving a variety of end tasks Question Answering, Search, etc.
- One approach train neural models from scratch
- Issue this involves two things
 - Modelling of Syntax and Semantics of the language
 - Modelling of the end-task
- Pretraining Learns the modelling of syntax and semantics through another task
- So the current model can focus exclusively on modelling of end-task

Pretraining - Masked Language Modelling

- How to pretrain?
- Which base task to choose:
 - Must have abundant data available
 - Must require learning of syntax and semantics
- Language Modelling (Self-supervision)
 - Does not require human annotated labels abundance of sentences
 - Requires understanding of both syntax and semantics to predict the next word in sentence

Encoder Summary

- Shallow NNs
 - Bag(words)
- Convolutional NNs
 - Handle bag (fixed length n-grams)
- Recurrent NNs
 - Handle small variable length histories
- LSTMs/GRUs
 - Handle larger variable length histories
- Bi-LSTMs
 - Handle larger variable length histories and futures
- Recursive NNs
 - Handle variable length partially ordered histories

Summary (contd)

- Hierarchical Recurrent NNs
 - RNN over RNNs (e.g., HRED)

- Neural language models
- Conditioned language models
 - Encoder-Decoder Models

- Attention models
 - attach non-uniform importance to histories based on evidence (question)

Prior Knowledge about Task

- Add as penalty in loss term
- Add as a hard constraint
- Add via architectural choice
- Add as a symbolic feature
- Supply through data augmentation

Deep Learning Strengths

- universal representation
- compositional representation
- feature discovery in task-driven way
- weight sharing in features
- seamlessly combine unsupervised w supervised
- natural fit for multi-modal and multi-task settings

Deep Learning Weaknesses

- high variance
- difficult to debug
- uninterpretable
- data hungry