1. If $S(n)$ is the space bound of skip list of $n$ elements, prove that $\text{Prob}[S(n) \geq cn] \leq 1 - 1/2^n$ for some constant $c$.

2. **A dart game** Imagine that an observer is standing at the origin of a real line and throwing $n$ darts at random locations in the positive direction. At point of time, only the closest dart is visible to the observer. What is the expected number of darts visible to the observer? Can you obtain a high-probability bound assuming independence between the throws? Can you apply this analysis to obtain an $O(n \log n)$ expected bound on quicksort?

3. Show that for any collection of hash function $H$, there exists $x, y$ such that
   \[ \sum_{h \in H} \delta_h(x, y) \geq |H|(\frac{1}{m} - \frac{1}{n}) \]
   where $n$ and $m$ are the sizes of universe and table respectively.
   Remarks: This justifies the definition of universal hash function.

4. Assume that the size of the table $T$ is a prime $m$. Partition a key $x$ into $r+1$ parts $x = <x_0, x_1 \ldots x_r>$ where $x_i < m$. Let $a = <a_0, a_1 \ldots a_r>$ be a sequence where $a_i \in \{0, 1, \ldots m-1\}$. We define a hash function $h_a(x) = \sum_i a_i x_i \mod m$. Clearly there are $m^{r+1}$ distinct hash functions. Prove that $\bigcup_a h_a$ forms a universal class of hash functions.

5. A collection of hash function $H$ is called **strongly** universal if for all keys $x, y$ and any $i, j \in [0..m-1]$
   \[ \text{Pr}_{h \in H}(h(x) = i \land h(y) = j) \leq \frac{c}{m^2} \]
   How does this differ from the earlier definition (in lecture)? Can you give an example of a strongly universal family?

6. Prove that for any (non-zero) vector over $\{0, 1\}$ of length $n$ when multiplied by a random $(0,1)$ vector (dot-product), the probability that it is 0 (summation is mod 2) is $\leq 1/2$.
   Use this fact to verify if for matrices $A, B, C$ ($n \times n$ with 0, 1 entries)
   \[ AB = C. \]
   Additions are mod 2 and your algorithm should run in $O(n^2)$ steps and be correct with probability $\geq 3/4$. (These kind of randomized algorithms are Monte Carlo).

7. Given a set of $n$ horizontal line segments, design a data structure that reports all intersections with a query vertical segment. Hint: Use segment trees.

8. Analyse the performance of range trees for reporting orthogonal range queries for dimensions $d \geq 3$. In particular what are the preprocessing space and query time?

9. If we allow for insertion and deletion of points, how does the performance of range trees get affected? In particular what are the time bounds for orthogonal range query, insertion and deletion of points? Discuss the data structure in details.

10. Design efficient algorithms to construct union and intersection of two convex hulls.
11. A point \( p_1 \geq p_2 \), \((p_1 \text{ dominates } p_2)\) if all the coordinates of \( p_1 \) is greater than all the coordinates of \( p_2 \). A \textit{maximal} point is one that is \textbf{not} dominated by any other point in a given set \( S \). The DOMINANCE problem is to find out all the maximal points in a given set \( S \).

(i) Design an \( O(n \log n) \) algorithm for the two dimensional DOMINANCE problem. (ii) Design an \( O(n \log n) \) algorithm for the three dimensional version of the DOMINANCE problem.