



Computational Geometry Lecture 7

Topic Convex hull

Convex set: $X \subseteq \mathbb{R}^2$ satisfies

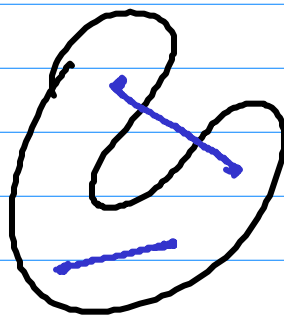
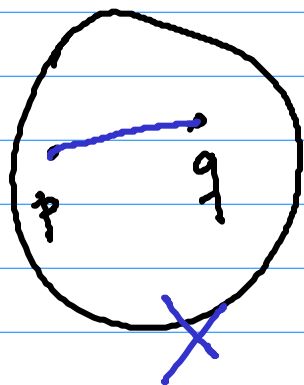
the following property

for any two points $p, q \in X$

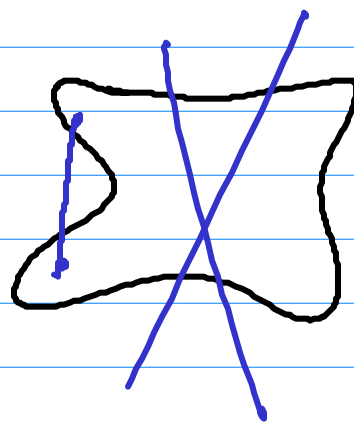
the convex linear combination, i.e.

$$\lambda \cdot p + (1-\lambda)q \in X \quad 0 < \lambda < 1$$

(the entire segment $\overline{pq} \subset X$)

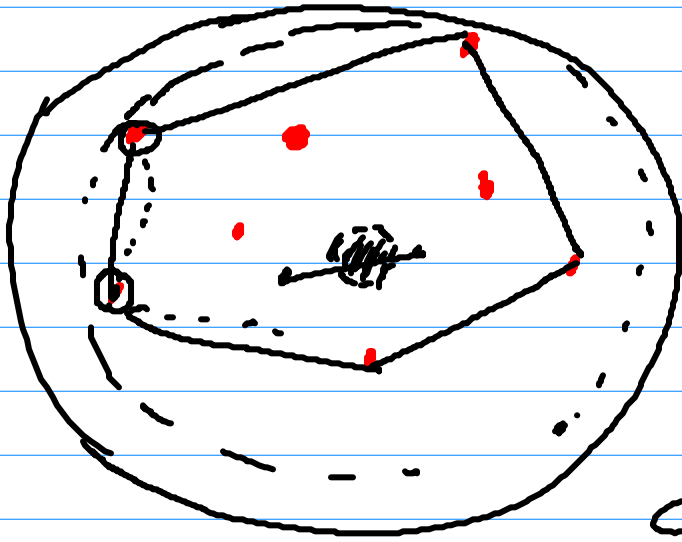


not
convex



Convex hull (S) S is a given set of objects
Suppose S is a finite set of points

The convex hull of S is - the smallest convex set that contains S .



It is a convex polygon

- It can be proved that the

$CH(S)$ is the

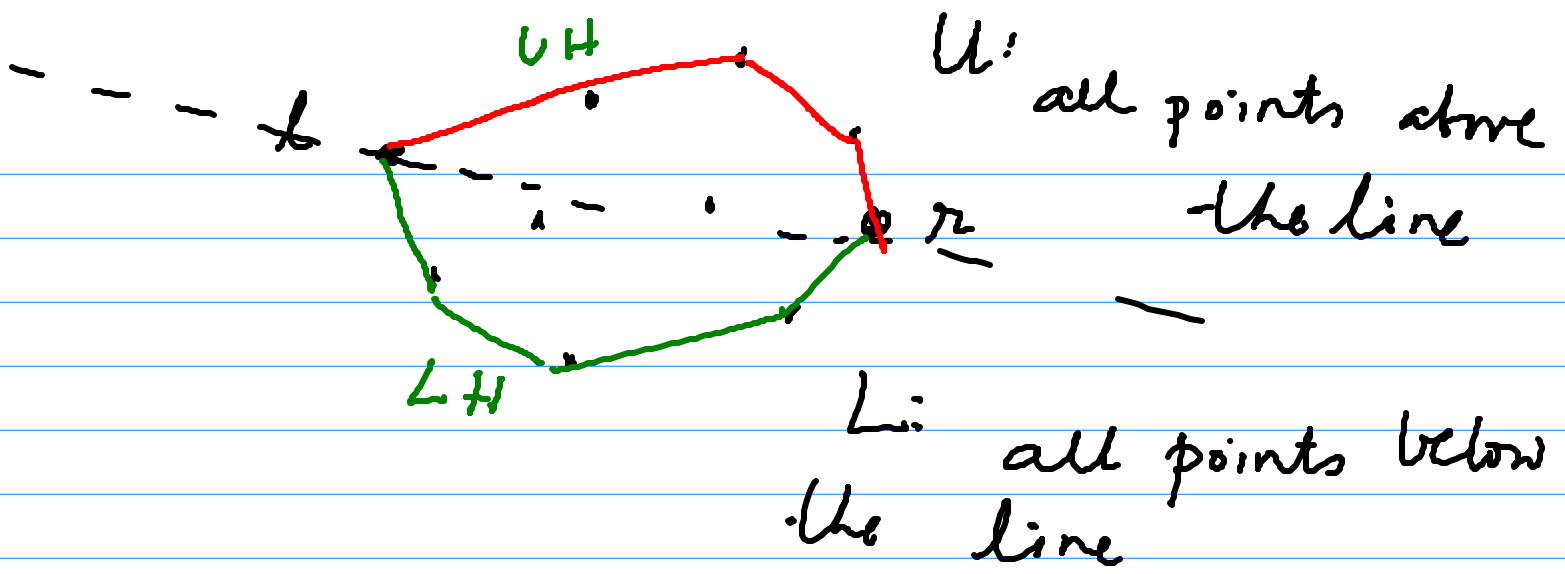
Smallest convex polygon containing S in terms of (i) area (ii) perimeter

Some points are on the boundary of the convex hull : Corner points / boundary points

The boundary of $CH(S)$ is an ordered chain (of vertices or edges)

Given a set S of n points, how do construct $CH(S)$?

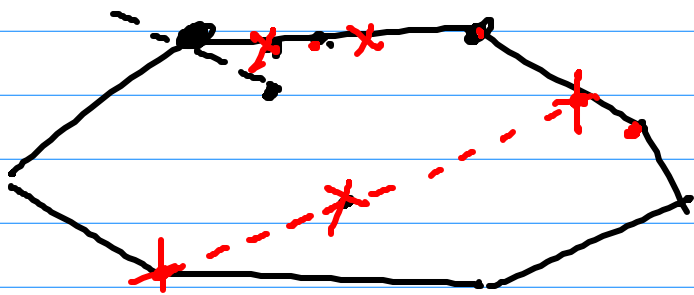
A boundary point supports a tangent i.e., a line that passes thru the point keeping the remaining points on one side.



How do we construct the upper hull?

Boundary point! (alternate defn)

A point $p \in S$ that cannot be expressed as a cdc of two points in the convex hull of S .



No point that is a cdc of two other points in $CH(S)$ is a **corner** point.

Computational Geometry Lecture 8

Topic: Convex hulls - continued

A point p is a c.h.c of points

$$q_1, q_2, \dots, q_k$$

if
$$p = \lambda_1 q_1 + \lambda_2 q_2 + \dots + \lambda_k q_k$$

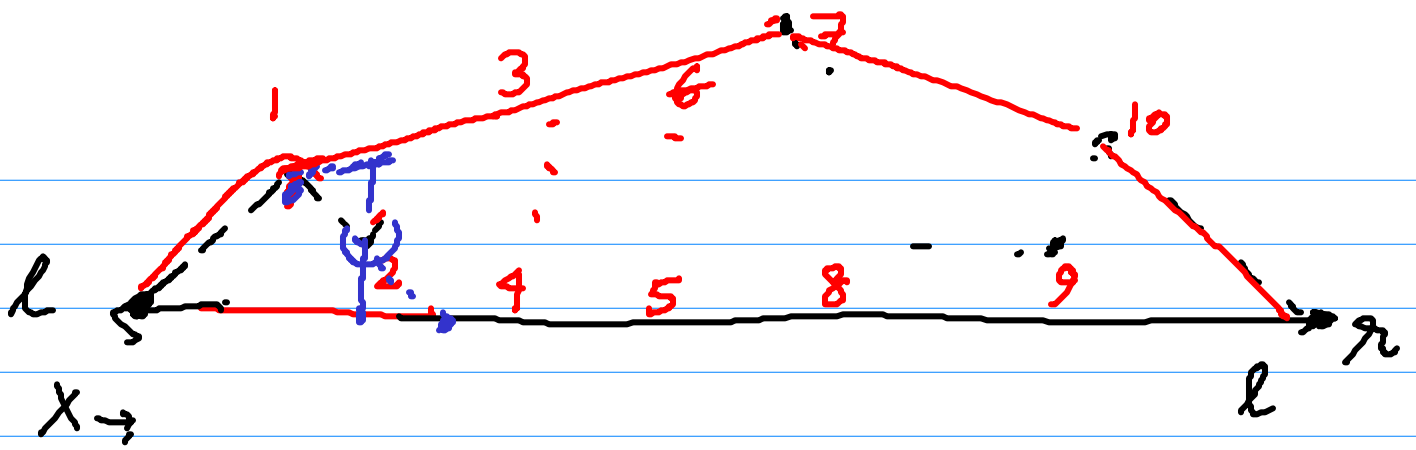
$$0 < \lambda_i < 1 \quad \sum_i \lambda_i = 1$$

$$q_1 \cdot q_2$$

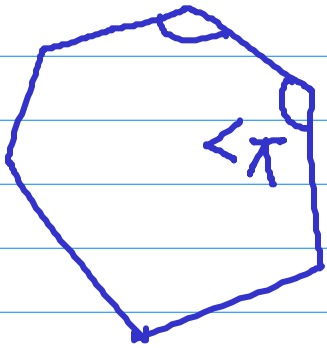
$$\cdot q_3$$

x

$$q_k \cdot$$



Monotone chain



$< \pi$: convex angle

$> \pi$ reflex angle

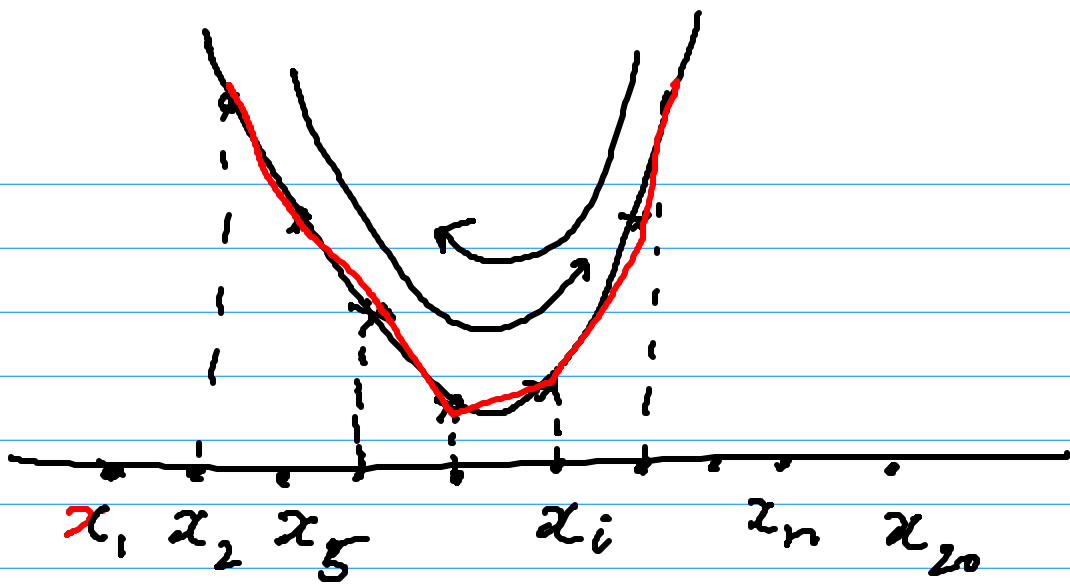
Running Time

- Sorting : $O(n \log n)$
- Constructing a Convex chain by adding-the next point or deleting.. ? parts

Since a point can be added or deleted once, using a stack, running-time (# left-turn / right turns) is $O(n)$.

Graham scan

Can we do better?



$$x_i \rightarrow (x_i, x_i^2) \quad \text{Given } S = \{x_1, x_2, \dots, x_n\}$$

$$S' = \{(x_1, x_1^2), (x_2, x_2^2), \dots\}$$

CH(S') gives us an ordered set of boundary points so that we can sort S using this ordering

$$\text{Sorting}(S) \sim O(n) \quad \text{CH}(S')$$

\therefore CH must have a lower bound of Sorting

$$P_1 \sim_{f(n)} P_2$$

lbnd of P_1 is applicable to P_2
and the ubnd of P_2 is " to P_1

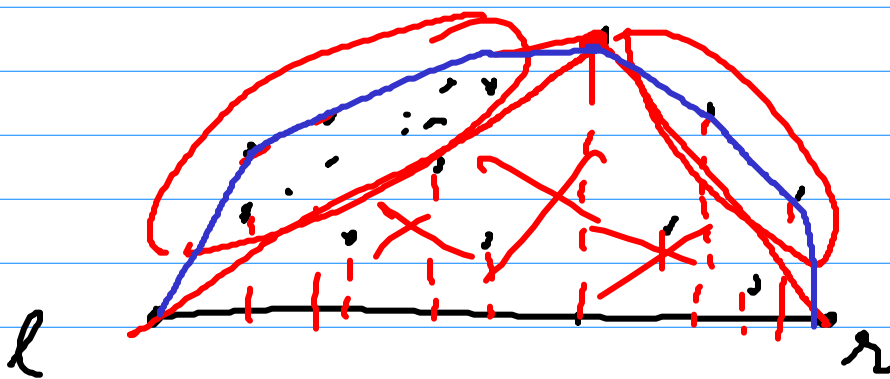
Observations on the lowerbound proof

1. We are assuming that CH algo must output ordered set of corner vertices.

(Instead of outputting the corner points in any order).

2. If all points are not on the boundary, i.e. only $h \ll n$

How about $O(n \log h)$? $\begin{matrix} \swarrow nh \\ \searrow n \log n \end{matrix}$



Quickhull

Running Time