

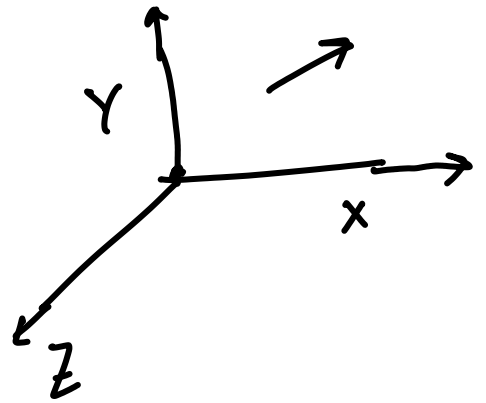
COL 702 lecture 3 July 30

---

How about maximal points in three dimensions?

Brute force in  $d$  dimensions will work correctly using

$$O(d \cdot n^2)$$



Sweeping by a plane  $\parallel$  to  $y-z$  in decreasing  $x$  coordinates

Obs . Point having max  $x$ -coord is maximal, say  $p$

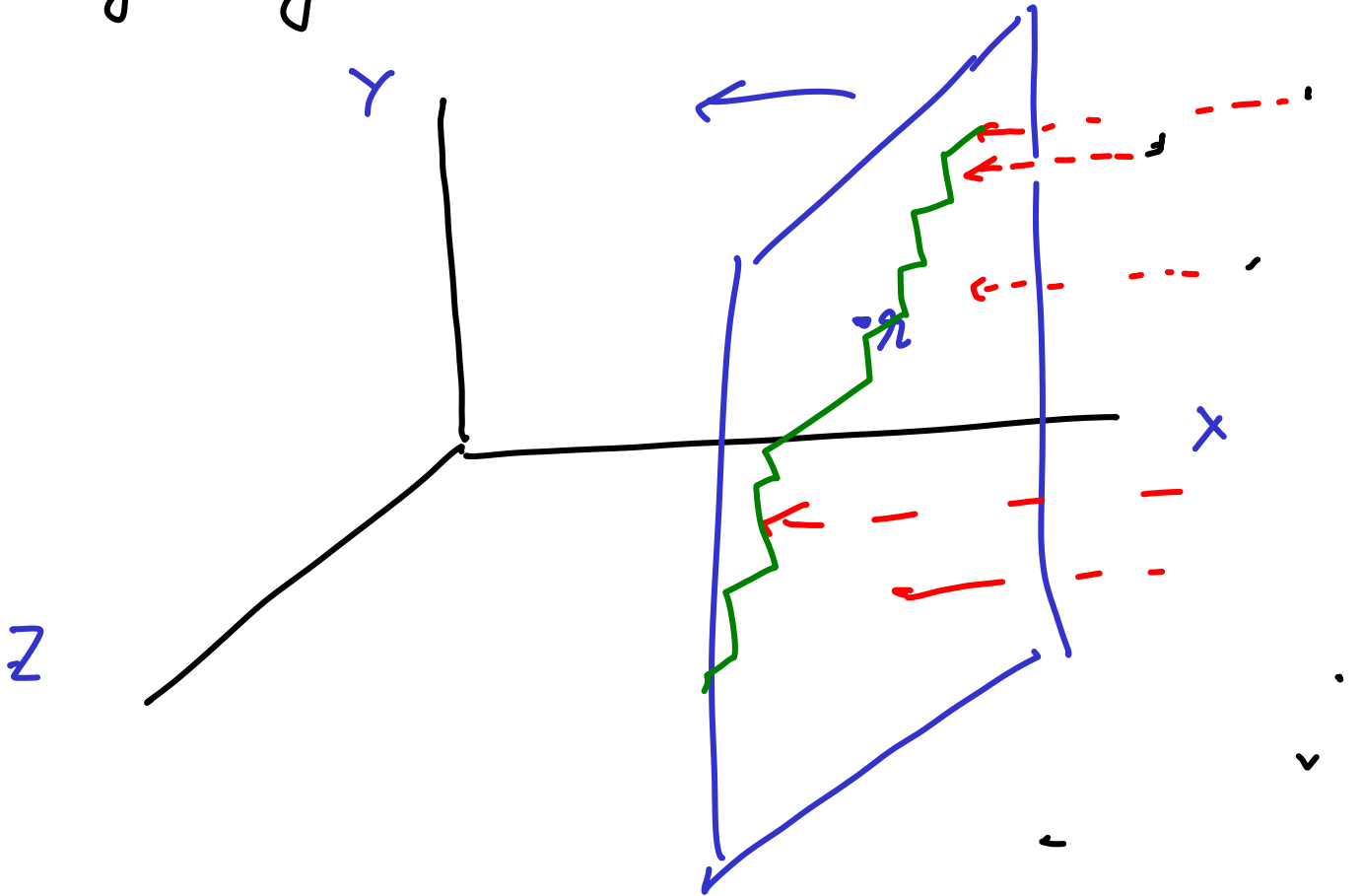
When we visit the next point, say  $q$

we know  $x(q) < x(p)$

$$y(q) : y(p)$$

$$z(q) : z(p)$$

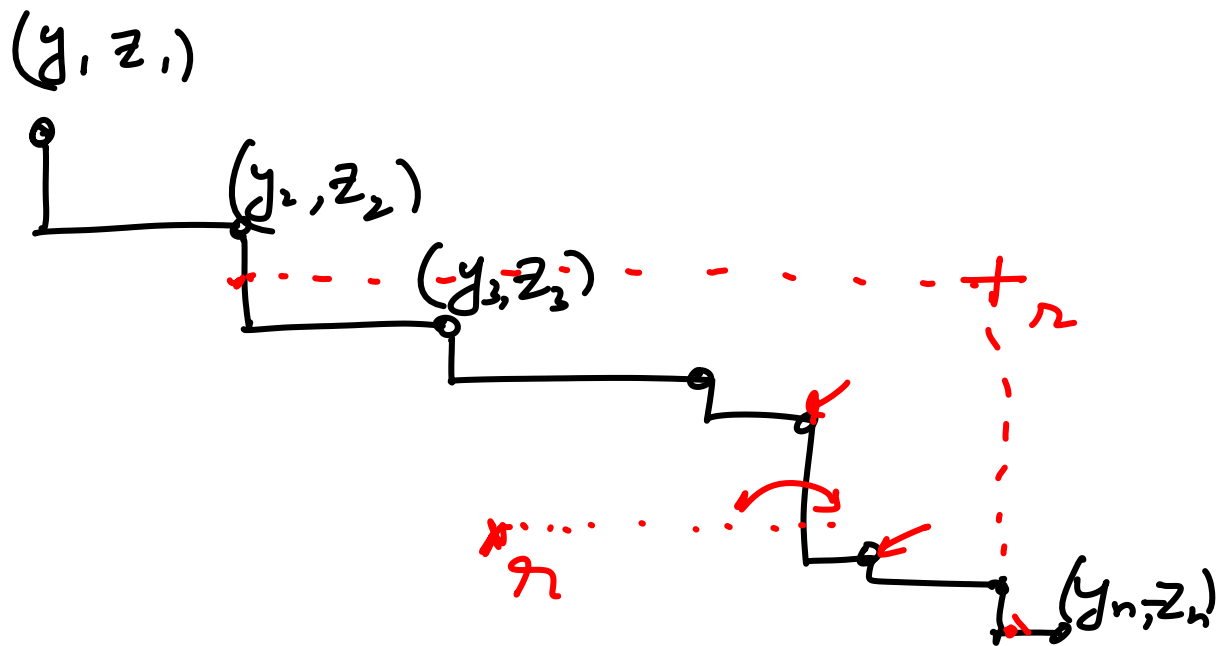
In the generic step, the latest point visited, say  $\pi$  will not be maximal if and only if one of the points visited previously has a higher  $y$  coordinate and a higher  $z$  coordinate



We want to test if  $\pi$  is inside or outside the staircase formed by the previously visited points

1. Can we do it quickly even if staircase is large?
2. Can we update the staircase quickly

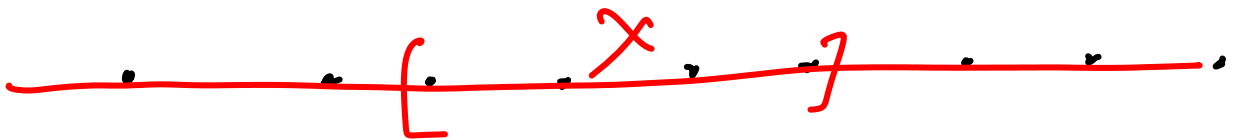
Problem : Design an efficient data structure for the staircase so that ① and ② can be supported



Given a Balanced BST,  
can we support insertions, search  
and "arbitrary # of deletions" in  
 $O(\log n)$  -time.

In general the following data  
structure operations on sorted sets  
are considered very useful

1. Splicing out an interval of points
2. Concatenating two sorted intervals  
into a single interval



Concatenable queues

In the staircase, we can delete  
the points one by one paying  
 $O(\log n)$  cost per deletion

One single iteration may be  
expensive (lots of points deleted)

but overall each point can  
be inserted or deleted at most once

$\Rightarrow O(n \log n)$  overall for 3D maxime

Amortized Analysis