

# Curves

**Polylines:** Piecewise linear approximation to curves



Not Smooth

# Curves

High degree approximation

- Explicit

$$y=f(x)$$

- Implicit

$$f(x,y)=0$$

- Parametric

$$x=x(t), y=y(t)$$

# Curves

## Explicit Representation

- $y = f(x)$
- Essentially a function plot over some interval  
 $x \in [a, b]$
- Simple to compute and plot
- Simple to check whether point lies on curve
- Cannot represent closed and multi-value curves

# Curves

## Implicit Representation

- Define curves implicitly as solution of equation system
  - Straight line in 2D:  $ax + by + c = 0$
  - Circle of radius  $R$  in 2D:  $x^2 + y^2 - R^2 = 0$
  - Conic Section:  $Ax^2 + 2Bxy + Cy^2 + 2Dx + 2Ey + F = 0$
- Simple to check whether point lies on curve
- Can represent closed and multi-value curves

# Curves

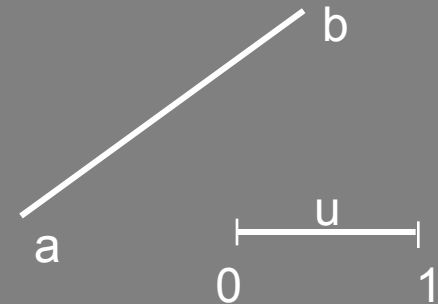
## Parametric Curves

- Describe position on the curve by a parameter

$$u \in \mathbb{R}$$

$$\Rightarrow \text{2D Curve } \mathbf{c}(u) = \{x(u), y(u)\}$$

$$\text{e.g., line : } \mathbf{c}(u) = (1-u)\mathbf{a} + u\mathbf{b}$$



- Hard to check whether point lies on curve
- Simple to render
- Can represent closed and multi-value curves

# Curves

## Parametric Curves

Parametric curves form a rich variety of free form smooth curves

They are modeled as piecewise polynomials and have two aspects:

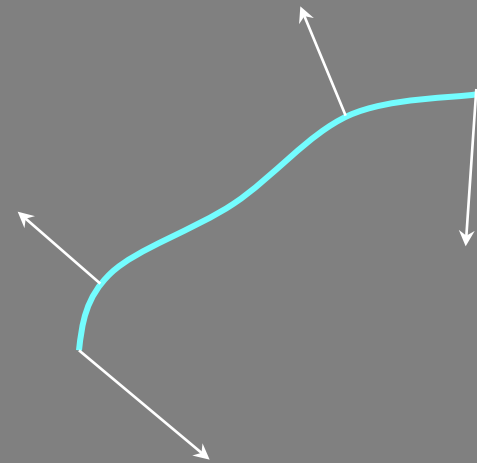
- Interpolation
- Approximation

*“Splines”*

# Curves

## Parametric Curves

## Splines



# Curves

## Parametric Curves

### Cubic Splines

$$P(t) = B_1 + B_2t + B_3t^2 + B_4t^3 \quad t_1 \leq t \leq t_2$$

$$= \sum_{i=1}^4 B_i t^{i-1}$$

$$x(t) = \sum_{i=1}^4 B_{ix} t^{i-1}$$

$$y(t) = \sum_{i=1}^4 B_{iy} t^{i-1}$$

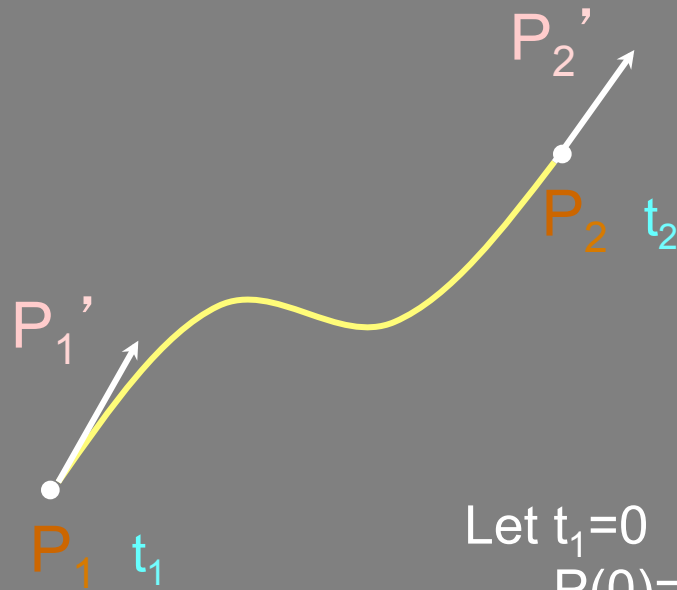
$$P'(t) = \sum_{i=1}^4 B_i (i-1) t^{i-2} = B_2 + 2B_3 t^1 + 3B_4 t^2$$



# Curves

## Parametric Curves

### Cubic Splines



Let  $t_1=0$

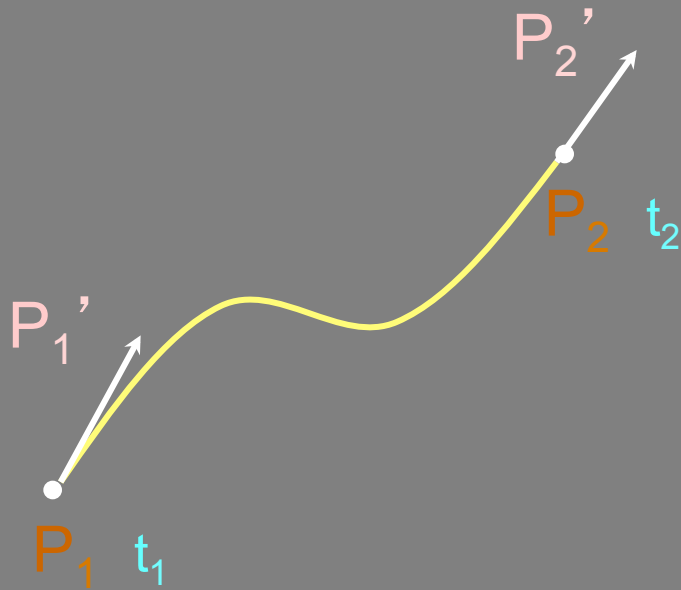
$$P(0)=P_1, \quad P(t_2)=P_2$$

$$P'(0)=P_1', \quad P'(t_2)=P_2'$$

# Curves

## Parametric Curves

### Cubic Splines



$$P(0) = B_1 = P_1$$

$$\begin{aligned} P(t_2) &= \sum_{i=1}^4 B_i t^{i-1} \Big|_{t=t_2} \\ &= B_1 + B_2 t_2^1 + B_3 t_2^2 + B_4 t_2^3 = P_2 \end{aligned}$$

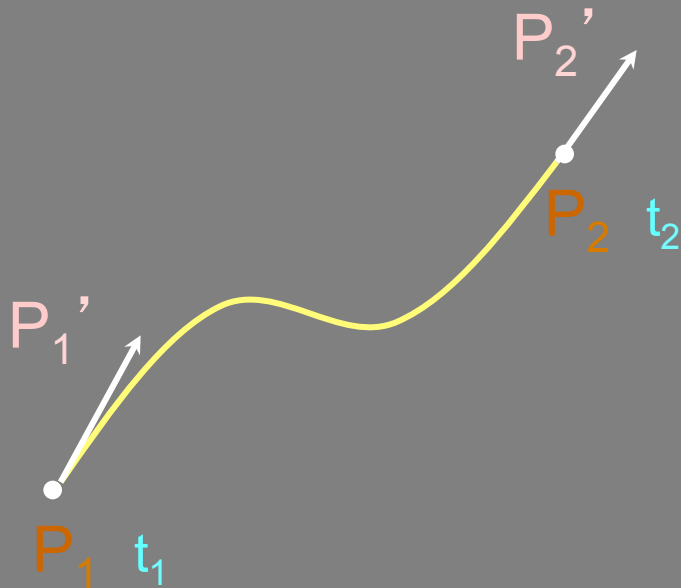
$$P'(0) = \sum_{i=1}^4 B_i (i-1) t^{i-2} \Big|_{t=0} = B_2 = P_1'$$

$$\begin{aligned} P'(t_2) &= \sum_{i=1}^4 B_i (i-1) t^{i-2} \Big|_{t=t_2} \\ &= B_2 + 2B_3 t_2^1 + 3B_4 t_2^2 = P_2' \end{aligned}$$

# Curves

## Parametric Curves

### Cubic Splines



Solving for  $B_1$   $B_2$   $B_3$  and  $B_4$

$$B_1 = P_1,$$

$$B_2 = P_1',$$

$$B_3 = \frac{3(P_2 - P_1)}{t_2^2} - \frac{2P_1'}{t_2} - \frac{P_2'}{t_2}$$

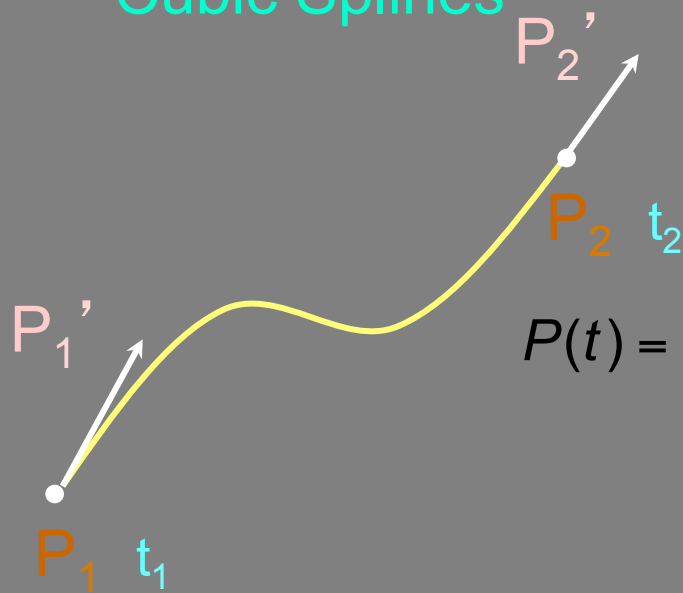
$$B_4 = \frac{2(P_1 - P_2)}{t_2^3} + \frac{P_1'}{t_2^2} + \frac{P_2'}{t_2^2}$$

Here  $P_1$  and  $P_2$  give the position of the endpoints and  $P_1'$  and  $P_2'$  give the direction of the tangent vectors.

# Curves

## Parametric Curves

### Cubic Splines



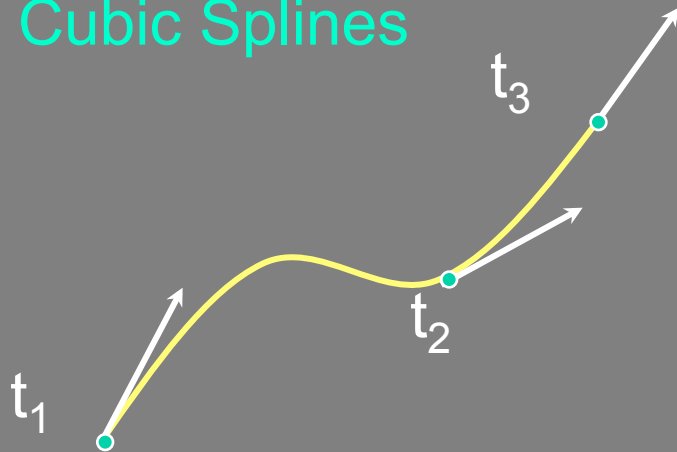
$$P(t) = P_1 + P_1' t + \left( \frac{3(P_2 - P_1)}{t_2^2} - \frac{2P_1'}{t_2} - \frac{P_2'}{t_2} \right) t^2 + \left( \frac{2(P_1 - P_2)}{t_2^3} + \frac{P_1'}{t_2^2} + \frac{P_2'}{t_2^2} \right) t^3$$

Thus, given the two end-points and the tangent vectors one can compute the cubic spline.

# Curves

## Parametric Curves

### Cubic Splines



Joining of Segments

2 SEGMENTS:  $P_1$   $P_2$   $P_3$  (Points)

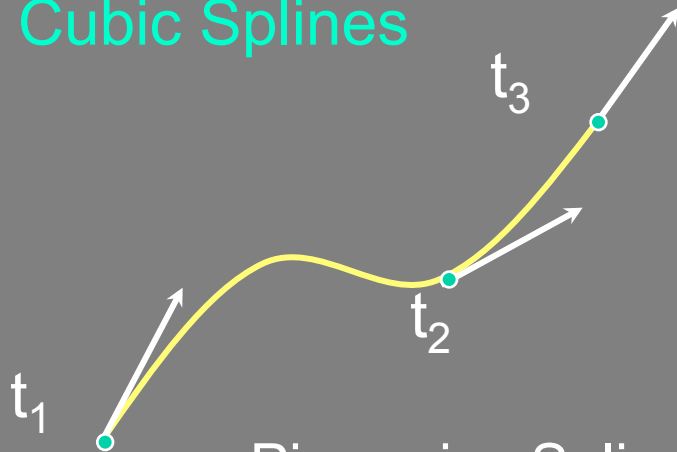
$P_1'$   $P_2'$   $P_3'$  (Tangents)

$P_2'$  is determined through the **continuity condition**

# Curves

## Parametric Curves

### Cubic Splines



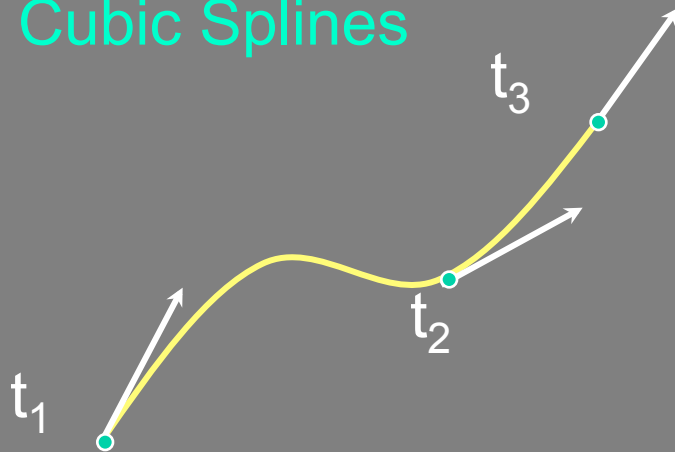
Piecewise Spline of degree  $k$  has continuity of order  $(k-1)$  at the internal joints.

Thus Cubic Splines have second order continuity i.e.  $P_2''(t)$  is continuous over the joint

# Curves

## Parametric Curves

### Cubic Splines



$$P''(t) = \sum_{i=1}^4 (i-1)(i-2)B_i t^{i-3} \quad t_1 \leq t \leq t_2$$

at  $t = t_2$

First segment

$$P'' = 6B_4 t_2 + 2B_3$$

Second segment

$$P'' = 2B_3$$

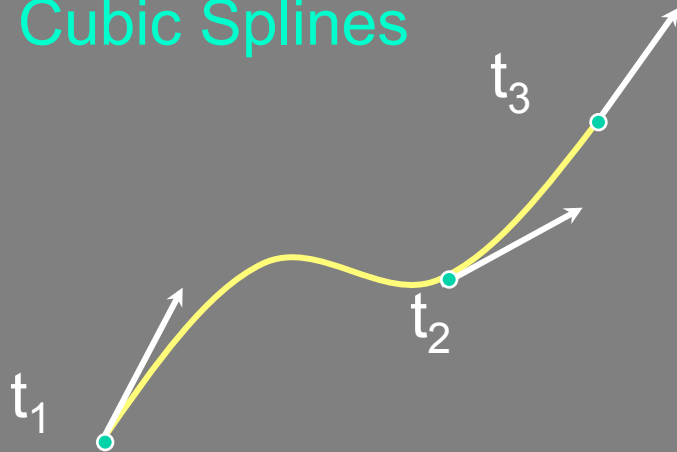
$$\text{So, } (6B_4 t_2 + 2B_3)_{\text{seg1}} = (2B_3)_{\text{seg2}}$$

Substitute the expressions for  $B_4$  and  $B_3$

# Curves

## Parametric Curves

### Cubic Splines



$$t_3 P_1' + 2(t_3 + t_2) P_2' + t_2 P_3' = \frac{3}{t_2 t_3} (t_2^2 (P_3 - P_2) + t_3^2 (P_2 - P_1))$$

$$\begin{bmatrix} t_3 & 2(t_3 + t_2) & t_2 \end{bmatrix} \begin{bmatrix} P_1' \\ P_2' \\ P_3' \end{bmatrix} = \frac{3}{t_2 t_3} (t_2^2 (P_3 - P_2) + t_3^2 (P_2 - P_1))$$



# Curves

## Parametric Curves

### Cubic Splines

In general, for the  $k$ th and  $(k+1)$ th segment ( $1 \leq k \leq n-2$ )

$$\begin{bmatrix} t_{k+2} & 2(t_{k+1} + t_{k+2}) & t_{k+1} \end{bmatrix} \begin{bmatrix} P_k' \\ P_{k+1}' \\ P_{k+2}' \end{bmatrix} = \frac{3}{t_{k+1}t_{k+2}} \left( t_{k+1}^2 (P_{k+2} - P_{k+1}) + t_{k+2}^2 (P_{k+1} - P_k) \right)$$

Set of  $n-2$  equations form a linear system for the tangent vectors  $P_k'$

# Curves

## Parametric Curves

### Cubic Splines

$$\begin{bmatrix} t_3 & 2(t_2 + t_3) & t_2 & 0 & \dots \\ 0 & t_4 & 2(t_3 + t_4) & t_3 & \\ \vdots & & \ddots & & \vdots \\ & \dots\dots\dots & t_n & 2(t_n + t_{n-1}) & t_{n-1} \end{bmatrix} \begin{bmatrix} P_1' \\ P_2' \\ \vdots \\ P_n' \end{bmatrix} = \begin{bmatrix} \frac{3}{t_2 t_3} (t_2^2 (P_3 - P_2) + t_3^2 (P_2 - P_1)) \\ \frac{3}{t_3 t_4} (t_3^2 (P_4 - P_3) + t_4^2 (P_3 - P_2)) \\ \vdots \\ \frac{3}{t_{n-1} t_n} (t_{n-1}^2 (P_n - P_{n-1}) + t_n^2 (P_{n-1} - P_{n-2})) \end{bmatrix}$$

# Curves

## Parametric Curves

### Cubic Splines

$$\begin{bmatrix} 1 & 0 & \dots & & & \\ t_3 & 2(t_2+t_3) & t_2 & & & \\ \vdots & t_4 & 2(t_3+t_4) & t_3 & \vdots & \\ \vdots & & \ddots & \ddots & \vdots & \\ & & & t_n & 2(t_n+t_{n-1}) & t_{n-1} \\ & & \dots & & 0 & 1 \end{bmatrix} \begin{bmatrix} P_1' \\ P_2' \\ \vdots \\ P_{n-1}' \\ P_n' \end{bmatrix} = \begin{bmatrix} P_1' \\ \frac{3}{t_2 t_3} (t_2^2 (P_3 - P_2) + t_3^2 (P_2 - P_1)) \\ \vdots \\ \frac{3}{t_{n-1} t_n} (t_{n-1}^2 (P_n - P_{n-1}) + t_n^2 (P_{n-1} - P_{n-2})) \\ P_n' \end{bmatrix}$$

# Curves

## Parametric Curves

### Cubic Splines

Solving for  $B_1$   $B_2$   $B_3$  and  $B_4$

$$B_{1k} = P_k,$$

$$B_{2k} = P'_k,$$

$$B_{3k} = \frac{3(P_{k+1} - P_k)}{t_{k+1}^2} - \frac{2P'_k}{t_{k+1}} - \frac{P'_{k+1}}{t_{k+1}}$$

$$B_{4k} = \frac{2(P_k - P_{k+1})}{t_{k+1}^3} + \frac{P'_k}{t_{k+1}^2} + \frac{P'_{k+1}}{t_{k+1}^2}$$

# Curves

## Parametric Curves

### Cubic Splines

$$\begin{bmatrix} B_{1k} \\ B_{2k} \\ B_{3k} \\ B_{4k} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -3/t_{k+1}^2 & -2/t_{k+1} & 3/t_{k+1}^2 & -1/t_{k+1} \\ 2/t_{k+1}^3 & 1/t_{k+1}^2 & -2/t_{k+1}^3 & 1/t_{k+1}^2 \end{bmatrix} \begin{bmatrix} P_k \\ P_k' \\ P_{k+1} \\ P_{k+1}' \end{bmatrix}$$

$$\begin{aligned} P_k(t) &= \sum_{i=1}^4 B_{ik} t^{i-1} & 0 \leq t \leq t_{k+1} \\ & & 1 \leq k \leq n-1 \\ &= \begin{bmatrix} 1 & t & t^2 & t^3 \end{bmatrix} \begin{bmatrix} B_{1k} & B_{2k} & B_{3k} & B_{4k} \end{bmatrix}^T \end{aligned}$$

# Curves

## Parametric Curves

### Cubic Splines

$P_k(t)$

$$= \begin{bmatrix} 1 & t & t^2 & t^3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -3/t_{k+1}^2 & -2/t_{k+1} & 3/t_{k+1}^2 & -1/t_{k+1} \\ 2/t_{k+1}^3 & 1/t_{k+1}^2 & -2/t_{k+1}^3 & 1/t_{k+1}^2 \end{bmatrix} \begin{bmatrix} P_k \\ P_k' \\ P_{k+1} \\ P_{k+1}' \end{bmatrix}$$

$$= \begin{bmatrix} (1 - 3t^2/t_{k+1}^2 + 2t^3/t_{k+1}^3) & (t - 2t^2/t_{k+1} + t^3/t_{k+1}^3) \\ (3t^2/t_{k+1}^2 - 2t^3/t_{k+1}^3) & (t^3/t_{k+1}^3 - t^2/t_{k+1}) \end{bmatrix} [P_k \quad P_k' \quad P_{k+1} \quad P_{k+1}']^T$$

# Curves

## Parametric Curves

### Cubic Splines

Substituting  $u=t/t_{k+1}$  rearranging

$$P_k(u) = [F_1(u) \ F_2(u) \ F_3(u) \ F_4(u)] [P_k \ P_{k+1} \ P_k' \ P_{k+1}']^T$$
$$0 \leq u \leq 1$$
$$1 \leq k \leq n-1$$

$$F_1(u) = 2u^3 - 3u^2 + 1$$

$$F_2(u) = -2u^3 + 3u^2$$

$$F_3(u) = u(u^2 - 2u + 1)t_{k+1}$$

$$F_4(u) = u(u^2 - u)t_{k+1}$$

$F_1, F_2, F_3, F_4$  are called the  
**Blending Functions**

# Curves

## Parametric Curves

### Cubic Splines

$$P_k(u)=[F][G]$$

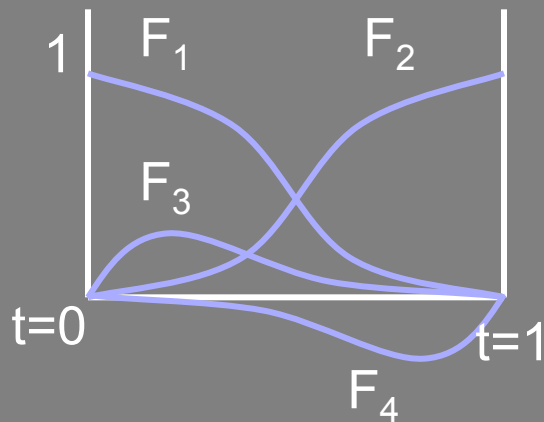
Where F is the Blending function matrix and G Is the geometric information.



# Curves

## Parametric Curves

### Cubic Splines



- $F_1(0)=1, F_2(0)=0, F_3(0)=0, F_4(0)=0$   
curve passes  $P_1$
- $F_1(1)=0, F_2(1)=1, F_3(1)=0, F_4(1)=0$   
curve passes  $P_2$
- $F_2=1-F_1, F_4=1-F_3$
- Relative magnitudes of  $F_1, F_2 > F_3, F_4$

# Curves

## Parametric Curves

### Cubic Splines

Piecewise Cubic Splines are determined by position vectors, tangent vectors and parameter value  $t_k$ .

The value of  $t_k$  can be chosen using either Chord Length parameterization or Uniform Parameterization.

If  $t_k=1$  for all  $k$  then the Spline is called Normalized Spline.

# Curves

## Parametric Curves

### Cubic Splines

Normalized Cubic Splines:  $t_k=1$  for all segments

The blending functions thus become

$$F_1(t) = 2t^3 - 3t^2 + 1, \quad F_2(t) = -2t^3 + 3t^2$$

$$F_3(t) = t^3 - 2t^2 + t, \quad F_4(t) = t^3 - t^2$$

These are called *Hermite Polynomial Blending* functions

$$\begin{bmatrix} F_1(t) \\ F_2(t) \\ F_3(t) \\ F_4(t) \end{bmatrix} = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

# Curves

## Parametric Curves

### Cubic Splines

The tridiagonal system for getting  $P'$  becomes

$$\begin{bmatrix} 1 & 0 & \dots\dots & & \\ 1 & 4 & 1 & & \\ \vdots & 1 & 4 & 1 & \vdots \\ \vdots & & \ddots & & \vdots \\ & & & 1 & 4 & 1 \\ & & \dots\dots & 0 & 1 \end{bmatrix} \begin{bmatrix} P_1' \\ P_2' \\ \vdots \\ \vdots \\ P_{n-1}' \\ P_n' \end{bmatrix} = \begin{bmatrix} P_1' \\ 3((P_3 - P_2) + (P_2 - P_1)) \\ \vdots \\ \vdots \\ 3((P_n - P_{n-1}) + (P_{n-1} - P_{n-2})) \\ P_n' \end{bmatrix}$$

# Curves

## Parametric Curves

### Cubic Splines

End Conditions as:

- Clamped:  $P_1', P_n'$  known
- Relaxed/Natural:  $P''(0) = 0$   
 $P''(t_n) = 0$
- Cyclic:  $P_1'(0) = P_n'(t_n)$   
 $P_1''(0) = P_n''(t_n)$
- Anticyclic:  $P_1'(0) = -P_n'(t_n)$   
 $P_1''(0) = -P_n''(t_n)$